
Power Supply Unit for Turbo Molecular Pump

**EI-D1003M
EI-D1103M
EI-D1303M
EI-D2003M
EI-D2203M
EI-D3203M
EI-D3403M
EI-D4203M**

INSTRUCTION MANUAL

**Carefully read and follow the instructions in the "Instruction Manual" before
operating the turbo molecular pump.
Keep the "Instruction Manual" in a safe and accessible place**

**SHIMADZU CORPORATION
Semiconductor Equipment Division**

Introduction

Thank you for choosing the EI-Dxx03M Power Supply Unit for Turbo Molecular Pump (hereafter referred to as "power supply unit" or "EI-Dxx03M"). Please read the instruction manual carefully before using the power supply unit, and save the instruction manual for future reference.

This instruction manual explains detailed operations of the power supply unit and cables. For instructions regarding the pump unit, please refer to the instruction manual for the pump unit to be used.

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In an effort to improve the product, this document may be revised in the future without notice.

Every effort has been made to prepare an accurate and complete manual, but if an error or omission should be discovered, revisions might not be possible immediately.

Shimadzu does not take responsibility for any effects that may result from the use of this manual.

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Precautions for Safe Operation

The instruction manual's nomenclature for warnings and precautions complies with the following safety warning symbols.

WARNING

Moderate level of attention required, failure to comply could possibly lead to serious injury or death.

CAUTION

Least level of attention required, failure to comply could possibly lead to injury and/or damage to the turbo molecular pump and/or power supply.

NOTICE

Not a hazard, instructions for safe operation of turbo molecular pump.

Strict adherence to all "WARNINGS" and "SAFETY PRECAUTIONS" is strongly recommended. Everyone associated with the operation of the turbo molecular pump is required to carefully read and follow all "WARNINGS" and "SAFETY PRECAUTIONS" listed in the Instruction Manual prior to the installation and/or operation of the turbo molecular pump. Information in greater detail can be found in the appropriate sections of the Instruction Manual.

WARNING

Turbo molecular pump repair and/or power supply repair can be very hazardous. Only trained technicians who are authorized by Shimadzu may do service of products.



WARNING

Neither overhaul nor modify the pump proper and power supply unit without admission. Doing so would impair safety of the pump proper.



WARNING

Decisions on system compatibility should be made by the system designer or the person deciding the specifications after conducting tests as necessary. The responsibility for guaranteeing the expected performance and safety of the system lies with the person who decides system compatibility.

CAUTION

The standard power input voltage of the power supply unit EI-Dxx03M (the "xx" number indicates the model of the corresponding pump) is AC 200 - 240 V \pm 10%. Connect the power supply unit to the voltage indicated on the rear panel label only. Connection of the power supply unit to the incorrect input voltage can cause damage to the equipment. Supply the power via a breaker (rating 15A). Please provide PE (Protective Earth) connection to the terminal of a "PE" marked wire in final application.

CAUTION

If an EI-Dxx03M power supply unit is used in combination with an existing pump that was operated in combination with a power supply unit not having the variable speed function (EI-xx03MD), the variable speed function cannot be used. (the "xx" number indicates the model of the corresponding pump.)

If the power supply unit is to be combined with an existing pump, modification and operational inspections are necessary. Please contact Shimadzu for detailed information.

CAUTION

The following "CAUTIONS" are to prevent operation anomalies.

1. Do not interrupt the electrical power operating the turbo molecular pump while the turbo molecular pump is in operation.
2. Do not connect or disconnect the turbo molecular pump control cable during the time the power supply is "ON".
3. Do not operate any equipment (i.e. drill motor, welding machine, etc.) that produces electromagnetic pollution, noise, etc., in the immediate proximity of an operating turbo molecular pumping system (pump, power supply, cables, etc).
4. When using the variable speed function to change the pump rotation rate, use a rotation rate that does not cause resonance with other devices installed at the site.

Explanation of caution marking



(1)HOT SURFACE : Risk of burn. (Notes 1)

- Keep off from touching surface of the pump as it is heated.
- Keep off from touching upper side surface of the power supply while the pump is in deceleration as it is heated.



(2)Do not remove cover, or else it may cause some changes inside and it is failed.



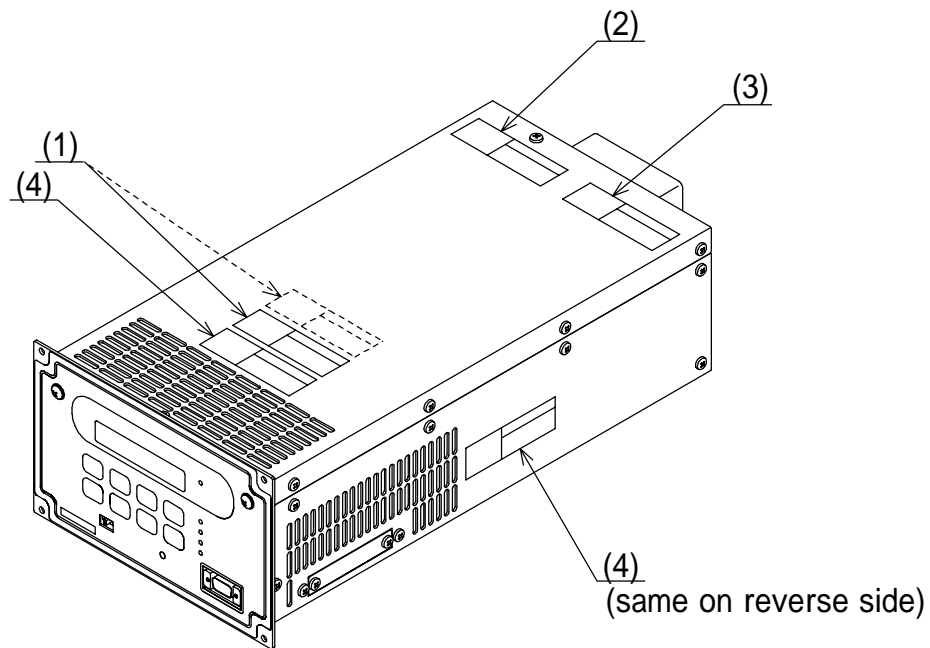
(3)Do not shut off ventilation, or else the inside of power supply get heated and it is failed.



(4)Be sure to use specified cable for this power supply. If not, it may cause connector be broken and power supply itself failed.

(Notes 1) The power supply units for some production lots come with a single nameplate, on which the name is indicated in both English and Japanese, whereas the power supply units for other production lots come with two nameplates, one in English and one in Japanese.

Location Where Caution Markings are Applied



Installation Precautions

Do not apply abnormal loads to the turbo molecular pump control cable plug and/or connector. Abnormal loads may cause cable disconnection.

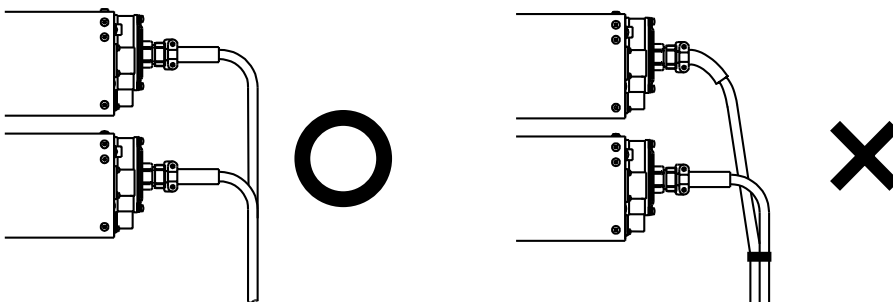
- (1) Do not pull the turbo molecular pump control cable by the connector or plug.



- (2) When installing the power supply unit into equipment, do not allow any electrical cables to be in tension or to have very tight bending radii.



- (3) Do not bundle the turbo molecular pump control cable with any cables.



- (4) Do not twist the turbo molecular pump control cable during connection.



Part Replacement

The lifetime of parts are specified as below.

The request for changing parts exceeding the estimated lifetime should be made to Shimadzu or an approved service company in order for safety and adequate performance of the pump and power supply unit.

Table 1 Estimated Part Life.

Parts List	Estimated Part Life
Transformer	10 years
Electrolytic condenser	5 years
Cooling fan	5 years
Button-type battery	10 years

Warranty

- 1) Products manufactured by Shimadzu are warranted against defects in material and workmanship for a period of twelve (12) months from the date of delivery from Shimadzu to the buyer.
- 2) Any modification to the product by the buyer or their agent voids this warranty.
- 3) Liability under this warranty is expressly, limited to replacement or repair (at Shimadzu's option) of defective parts.
- 4) Shimadzu may at any time discharge its warranty as to any of its products by refunding the purchase price and taking back the products.
- 5) This warranty applies only to parts manufactured, and labor provided, by Shimadzu under valid warranty claims received by Shimadzu within the applicable warranty period and shall be subject to the terms and conditions hereof.
- 6) Malfunctions caused by abuse or neglect of the product are expressly not covered by this warranty.
- 7) Shimadzu expressly disclaims responsibility for any loss or damage caused by the use of its products other than in accordance with proper operating and safety procedures. Responsible care must be taken by the user to avoid hazards.
- 8) Unless otherwise specified, in-warranty repaired or replacement parts are warranted only for the remaining unexpired portion of the original warranty period applicable to the parts, that have been repaired or replaced.
- 9) Damage or malfunction to the Shimadzu TMP product, directly or indirectly caused by natural disasters, such as, but not limited to, earthquakes, hurricanes, tornadoes, typhoons, and the like, will not be covered by this warranty.
- 10) Except as stated herein, Shimadzu makes no warranty, expressed or implied (either in fact or by operation of law), statutory or otherwise: And, except as stated herein, Shimadzu shall have no liability for special or consequential damages of any kind or from any cause arising out of the sale, installation, or use of any of its products.
- 11) Statements made by any person, including representatives of Shimadzu, which are inconsistent or in conflict with the terms of this warranty shall not be binding upon Shimadzu unless reduced to writing and approved by an officer of Shimadzu.

Disposal of Products and Parts

When disposing of the product or its accessories, please contact the Shimadzu service representative. Improper disposal of the product or its accessories may cause environmental contamination.



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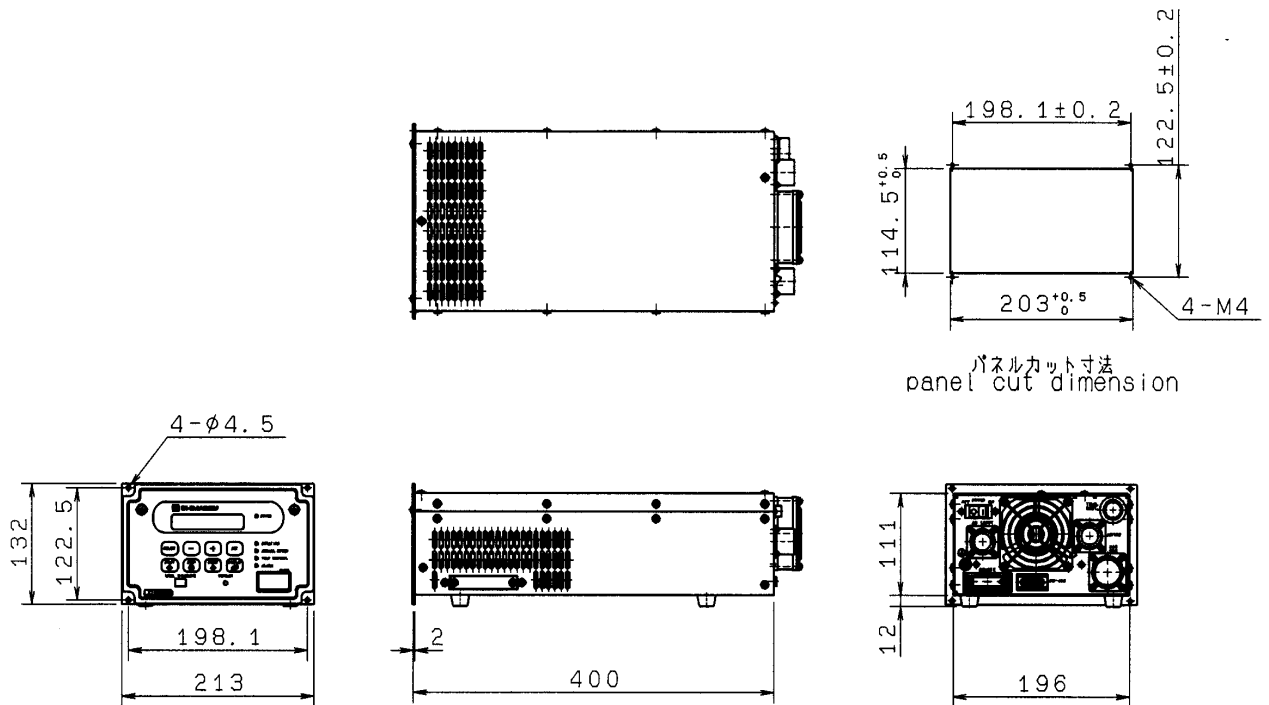
OUTLINE AND DESCRIPTIONS

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- 1.1 Outline
- 1.2 Descriptions
 - 1.2.1 Power Supply Unit
 - 1.2.2 Control Cable
 - 1.2.3 Motor Cable
 - 1.2.4 Standard Accessories

1.2 Descriptions

1.2.1 Power Supply Unit



Description	Parts number
EI-D1003M	262-78689-02
EI-D1103M	262-78690-02
EI-D1303M	262-78688-02
EI-D2003M	262-78691-02
EI-D2203M	262-78692-02
EI-D3203M	262-78685-02
EI-D3403M	262-78694-02
EI-D4203M	262-78696-02

Fig.1-1 Outside Dimensions of Power Supply Unit

1.2.2 Control Cable

The cable can be selected from the following.

Description	Note	Parts number
Control Cable	3 meters length, straight plugs for both sides.	262-78187-03
	5 meters length, straight plugs for both sides.	262-78187-05
	7 meters length, straight plugs for both sides.	262-78187-07
	10 meters length, straight plugs for both sides.	262-78187-10
	15 meters length, straight plugs for both sides.	262-78187-15
	20 meters length, straight plugs for both sides.	262-78187-20
	30 meters length, straight plugs for both sides.	262-78187-30

1.2.3 Motor Cable

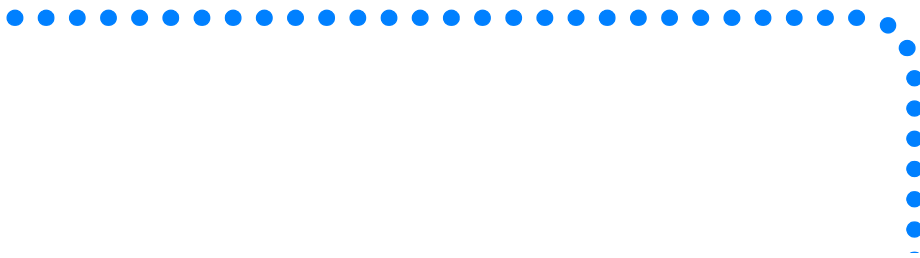
The cable can be selected from the following

Description	Note	Parts number
Motor Cable	(for Air cooled type and Air cooled chemical type)	
	3 meters length, straight plugs for both sides.	262-76410-03
	5 meters length, straight plugs for both sides.	262-76410-05
	7 meters length, straight plugs for both sides.	262-76410-07
	10 meters length, straight plugs for both sides.	262-76410-10
	15 meters length, straight plugs for both sides.	262-76410-15
	20 meters length, straight plugs for both sides.	262-76410-20
	30 meters length, straight plugs for both sides.	262-76410-30
	(for Wide range type and Wide range chemical type)	
	3 meters length, straight plugs for both sides.	262-76409-03
	5 meters length, straight plugs for both sides.	262-76409-05
	7 meters length, straight plugs for both sides.	262-76409-07
	10 meters length, straight plugs for both sides.	262-76409-10
	15 meters length, straight plugs for both sides.	262-76409-15
	20 meters length, straight plugs for both sides.	262-76409-20
30 meters length, straight plugs for both sides.	262-76409-30	

1.2.4 Standard Accessories

	Description	Q'ty	Notes	Parts Number
1	Power cable	1	5meters length	262-76773-05
2	Remote Control Connector	1	MR-34MG (Pin type connector) MR-34L4 (Connector hood)	070-50791-63 070-50792-75
3	Insstruction Manual	1		263-13228

IDENTIFICATION AND FUNCTION



2.1 Power Supply Unit

2.1 Power Supply Unit

2

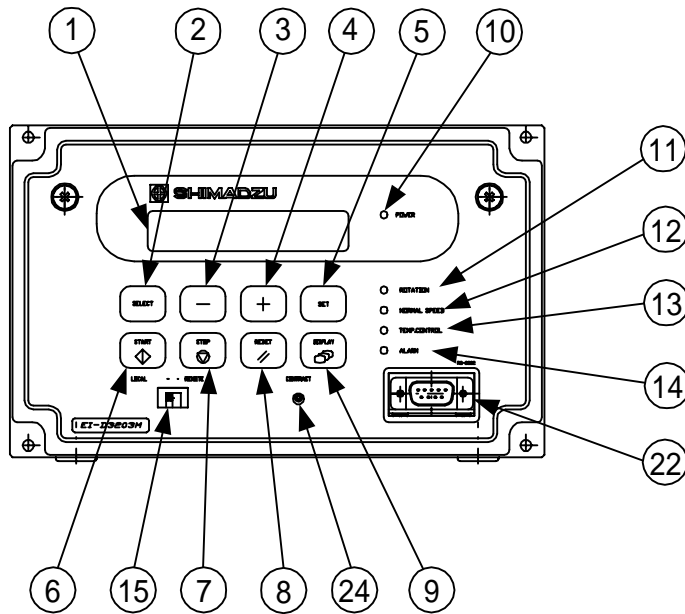


Fig.2-1 Front Control Panel

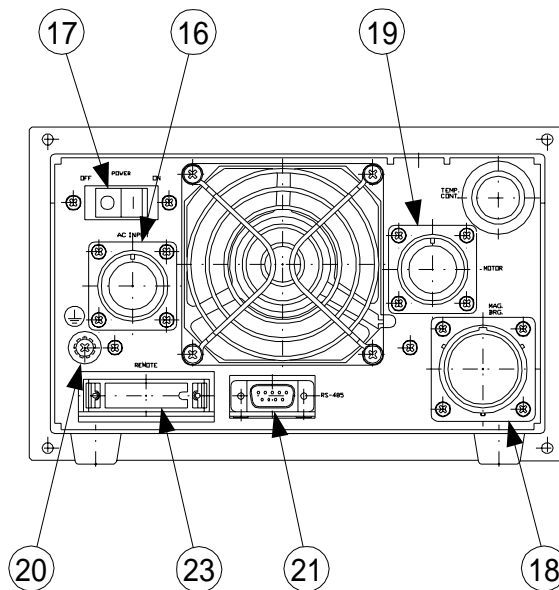
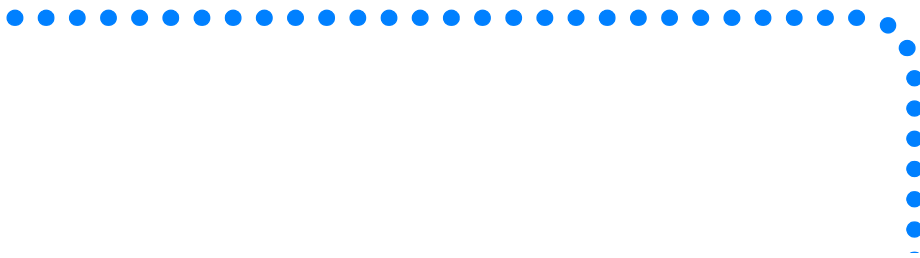


Fig.2-2 Rear Panel

- (1) LCD - - - - - Display operation monitor, alarm contents, settings (see Section 6.6 "Software Operation")
- (2) SELECT KEY - - - - - LCD display operation key, select menu
- (3) + KEY - - - - - LCD display operation key, previous menu or addition
- (4) - KEY - - - - - LCD display operation key, next menu or subtraction
- (5) SET KEY - - - - - LCD display operation key, set menu
- (6) START SWITCH - - - - - Press to start rotation of the pump's rotor.
- (7) STOP SWITCH - - - - - Press to apply the brake to stop rotation of the pump's rotor.
- (8) RESET SWITCH - - - - - Press to stop the buzzer after an alarm or warning occurs. After remedying the cause of the alarm, press the RESET switch again to turn off the ALARM lamp. However, the buzzer sounds again if the RESET switch is pressed again before the cause of the alarm is remedied.
- (9) DISPLAY SWITCH - - - - - LCD display operation key, change display mode.
- (10) POWER LAMP - - - - - Power On indicator lamp (green)
- (11) ROTATION LAMP - - - - - Operation indicator lamp indicating that the pump's rotor is running (green)
- (12) NORMAL SPEED LAMP - - - - - Operation indicator lamp indicating that the pump's rotor is rotating normally (green)
- (13) TEMP. CONTROL LAMP - - - - - Not used with EI-Dxx03M.
- (14) ALARM LAMP - - - - - Alarm/warning lamp (yellow). See 10.6 "Alarm Detection Capabilities." Lights when an alarm occurs or flashes to give a warning.
- (15) REMOTE/LOCAL SELECTION SWITCH - Remote/Local selection switch; The remote mode allows the turbo molecular pump to be controlled by employing the external control connector (24) or serial interface connector ((22), (23)), located on the rear panel of the power supply unit. The local mode allows controlling the turbo molecular pump from the front panel
- (16) AC INPUT CONNECTOR - - - - - Power cable receptacle
- (17) POWER SWITCH - - - - - Power switch
- (18) CONTROL CONNECTOR - - - - - Control cable receptacle
- (19) MOTOR CONNECTOR - - - - - Motor cable receptacle
- (20) EARTH GROUND - - - - - Electrical grounding terminal
- (21) RS-485 CONNECTOR - - - - - Serial interface connector (Note 1)
- (22) RS-232C CONNECTOR - - - - - Serial interface connector (Note 1)
- (23) REMOTE CONNECTOR - - - - - Remote-control connector
- (24) CONTRAST - - - - - Adjusts the contrast of the LCD
- (Note 1) See APPENDIX-A "COMMUNICATIONS" for details.

CONSTRUCTION AND PRINCIPLE



3.1 Power Supply Unit

3.1 Power Supply Unit

3

The power supply unit is composed of the magnetic bearing control system and the high frequency motor system and does not use back up batteries for electrical power failure.

The magnetic bearing control system controls the levitation of the rotor inside the turbo molecular pump. The system detects the rotor position by an electrical signal received from the gap sensors and maintains the levitation by regulating the current to the magnetic bearings.

The high frequency motor system rotates the rotor at a rated rotational speed. This frequency power system converts AC/single phase commercial power to controlled DC/three phase pulsed power. The DC/three phase pulsed power drives the DC motor that is an integral part of the rotor. If the electrical power is interrupted while the rotor is in a high-speed rotation, then the motor becomes a generator to power the magnetic bearing system during a power failure deceleration mode; therefore, the need for a battery backup system is eliminated.

The power supply unit is equipped with an RS-232C and an RS-485 serial interface and with Contact input/output to operate the turbo molecular pump from an external source. The operational status can be monitored and the history retrieved through the RS-232C and RS-485. See APPENDIX-A "COMMUNICATIONS" for instructions to remotely operate the turbo molecular pump using the RS-232C and RS-485 serial interface.

The turbo molecular pump, the power supply, the control cable, and the motor cable are respectively interchangeable among any products of the same model.

Fig.1-1 shows the external dimensions of the power supply unit.

The power supply unit, control cable, motor cable, and the pump unit are all mutually compatible. However, only pumps and power supply units with the same series number (the "xx" number) are compatible with each other.

SPECIFICATIONS



- 4.1 Power Supply Unit
- 4.2 Standards Fulfilled

4.1 Power Supply Unit

Power supply unit		EI-D1003M		EI-D1103M	EI-D1303M
Suitable pump		TMP-803M TMP-803MC TMP-803LM TMP-803LMC	TMP-1003M TMP-1003MC TMP-1003LM TMP-1003LMC	TMP-1103MP TMP-1103MPC TMP-1103LMP TMP-1103LMPC	TMP-1303M TMP-1303MC TMP-1303LM TMP-1303LMC
Exchangeable Compatibility		The control cable and the motor cable are interchangeable between any pump and power supply unit.			
Magnetic Bearing		5 axis control. No Battery is required. (When power failure occur, magnetic bearing is support by regenerative power from motor.)			
Speed control		Feedback control			
Speed variation		Speed is variable between 25% and 100% of the rated speed (set as 0.1%).			
Display	LCD	20characters*2 lines (With LED back light)			
	LED	POWER / ROTATION / NORMAL SPEED / ALARM			
Communication	Contact	REMOTE (MR 34pin) Input : START / STOP / RESET / LOW SPEED Output : ROTATION / ACC. / BRAKE / NORMAL REMOTE / ALARM / WARNING			
	Serial	RS-232C (D-sub 9pin male) / RS-485 (D-sub 9pin female)			
Alarm Detection	Alarm	Pump Temperature Pump Startup Failure,Overload,Overspin for motor Magnetic Bearing failure Power supply malfunction (Over Temperature inside power supply, Fail drive circuit) Power failure			
	Warning	Failure of magnetic bearing			
Protection	Alarm	ALARM LED lights, buzzer sounds, alarm description displayed on LCD. Power failure: Decelerates while maintaining magnetic levitation by regenerative breaking power. Levitation is stopped after deceleration, and the rotor is supported by the touch-down bearing. Once power is restored, restart is possible after resetting. (Refer to Section 7.2) When other alarms occur: Stops operation or decelerates. Magnetic levitation is continued			
	Warning	ALARM LED flashes, buzzer sounds, warning description displayed on LCD.Pump operation continues.			
Momentary power failure		If the electrical power is recovered in 1 second or less, then the power supply operation prior to the electrical power failure is continued. No change output signal.Otherwise, the turbo molecular pump rotor is decelerated. If the power is disrupted over one second, the brake will engage. The pump can be restarted after the reset operation.			
Alarm history		Stores the date, time and detected event information for the last 99 alarm events.			
Input electric power	Voltage	Single phase 200 to 240 VAC \pm 10% (50 / 60 Hz \pm 2 Hz)			
	Maximum power	1.0 kVA	1.0 kVA	1.0 kVA	1.0 kVA
	Insulation withstand voltage	1500 V , 1 minutes			
Mass		8 kg			

4.1 Power Supply Unit

Power supply unit		EI-D1003M	EI-D1103M	EI-D1303M
Environmental Conditions	Temperatures	Operation : 0 to 45 / Storage : -25 to 70 (No dew condensation)		
	Relative humidity	40 to 80 %RH		
Installation conditions (See EN61010-1 standard)		Use : Indoor, Altitude max : 2000 m Overvoltage category III, Pollution degree 2 IP classification 20		

4

Power supply unit		EI-D2003M	EI-D2203M	EI-D3203M	EI-D3403M	EI-D4203M
Suitable pump		TMP-2003M TMP-2003MC TMP-2003LM TMP-2003LMC	TMP-2203M TMP-2203MC TMP-2203LM TMP-2203LMC	TMP-3203M TMP-3203MC TMP-3203LM TMP-3203LMC	TMP-3403LMC	TMP-4203LMC
Exchangeable Compatibility		The control cable and the motor cable are interchangeable between any pump and power supply unit.				
Magnetic Bearing		5 axis control. No Battery is required. (When power failure occur, magnetic bearing is support by regenerative power from motor.)				
Speed control		Feedback control				
Speed variation		Speed is variable between 25% and 100% of the rated speed (set as 0.1%).				
Display	LCD	20characters*2 lines (With LED back light)				
	LED	POWER / ROTATION / NORMAL SPEED / ALARM				
Communication	Contact	REMOTE (MR 34pin) Input : START / STOP / RESET / LOW SPEED Output : ROTATION / ACC. / BRAKE / NORMAL REMOTE / ALARM / WARNING				
	Serial	RS-232C (D-sub 9pin male) / RS-485 (D-sub 9pin female)				
Alarm Detection	Alarm	Pump Temperature Pump Startup Failure,Overload,Overspin for motor Magnetic Bearing failure Power supply malfunction (Over Temperature inside power supply, Fail drive circuit) Power failure				
	Warning	Failure of magnetic bearing				
Protection	Alarm	ALARM LED lights, buzzer sounds, alarm description displayed on LCD. Power failure: Decelerates while maintaining magnetic levitation by regenerative breaking power. Levitation is stopped after deceleration, and the rotor is supported by the touch-down bearing. Once power is restored, restart is possible after resetting. (Refer to Section 7.2) When other alarms occur: Stops operation or decelerates. Magnetic levitation is continued				
	Warning	ALARM LED flashes, buzzer sounds, warning description displayed on LCD.Pump operation continues.				
Momentary power failure		If the electrical power is recovered in 1 second or less, then the power supply operation prior to the electrical power failure is continued. No change output signal.Otherwise, the turbo molecular pump rotor is decelerated. If the power is disrupted over one second, the brake will engage. The pump can be restarted after the reset operation.				
Alarm history		Stores the date, time and detected event information for the last 99 alarm events.				

SECTION 4 SPECIFICATIONS

Power supply unit		EI-D2003M	EI-D2203M	EI-D3203M	EI-D3403M	EI-D4203M
Input electric power	Voltage	Single phase 200 to 240 VAC \pm 10% (50 / 60 Hz \pm 2 Hz)				
	Maximum power	1.2 kVA	1.2 kVA	1.2 kVA	1.3 kVA	1.5 kVA
	Insulation withstand voltage	1500 V , 1 minutes				
Mass		8 kg				
Environmental Conditions	Temperatures	Operation : 0 to 45 / Storage : -25 to 70 (No dew condensation)				
	Relative humidity	40 to 80 %RH				
Installation conditions (See EN61010-1 standard)		Use : Indoor, Altitude max : 2000 m Overvoltage category III, Pollution degree 2 IP classification 20				

4

4.2 Standards Fulfilled

Safety	EN61010-1; 2001 UL61010A-1:2002 R4.02 SEMI S2-1102 EN1012-2; 1996
EMC	EN61326-1; 1997 + A1; 1998 + A2; 2001 class A EN61000-3-2; 1995 + A14; 2000 SEMI F47-0200

INSTALLATION



- 5.1 Installation of the Power Supply Unit
 - 5.1.1 Location of the Power Supply Unit
 - 5.1.2 Installation of the Power Supply Unit
 - 5.1.3 Compatibility with Previous Models
- 5.2 Connection of Power Cable
- 5.3 Connection of the Pump to the Power Supply Unit

5.1 Installation of the Power Supply Unit

5.1.1 Location of the Power Supply Unit

5

Install and anchor the power supply unit inside a rack, which shall be located at a place where it is not exposed to direct sun ray and well ventilated. Avoid to locate it at the following places.

- (1) Place where it is very humid, dusty and, in addition, oil smoke, vapor, water, etc, are exist.
- (2) Place where the power supply unit is exposed to direct sun ray and abnormally high temperature
- (3) Place with high amplitude of vibration and impact
- (4) Near chemically active gas and explosive/combustible gas
- (5) Place with strong magnetic field and electric field, noisy place, and place with strong radioactive ray
- (6) Unventilatable place

5.1.2 Installation of the Power Supply Unit

When mounting the power supply unit onto the customer's rack, use the front panel installation holes. The installation panel and screws are to be supplied by the customer.

Prepare the shelf to support the weight of the power supply unit in the rack.

How to install the unit onto a rack

- (1) Turn the power supply unit over and remove the four rubber pads.
- (2) Pass the power supply unit through the cutout hole in the installation panel and secure it with four screws (See Fig. 5-2).
- (3) In order to ensure that the interior of the power supply unit is cooled sufficiently, leave a gap inside the rack of at least 30 mm above, 5 mm on either side, and 50 mm to the rear of the power supply unit (See Fig. 5-1).
- (4) The space required for installing the cables is shown in Fig. 5-4.
- (5) Reattach the rubber pads if necessary.

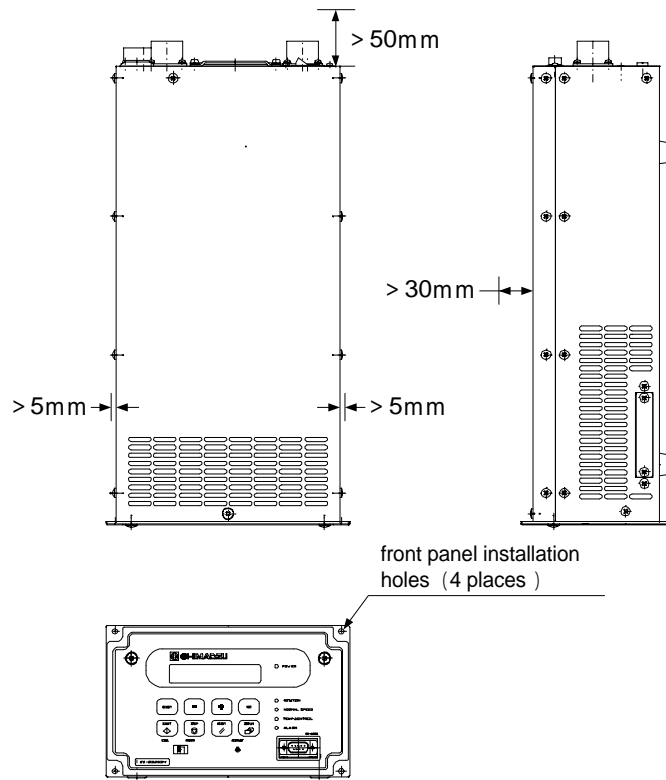


Fig.5-1 Leave enough space around the power supply unit

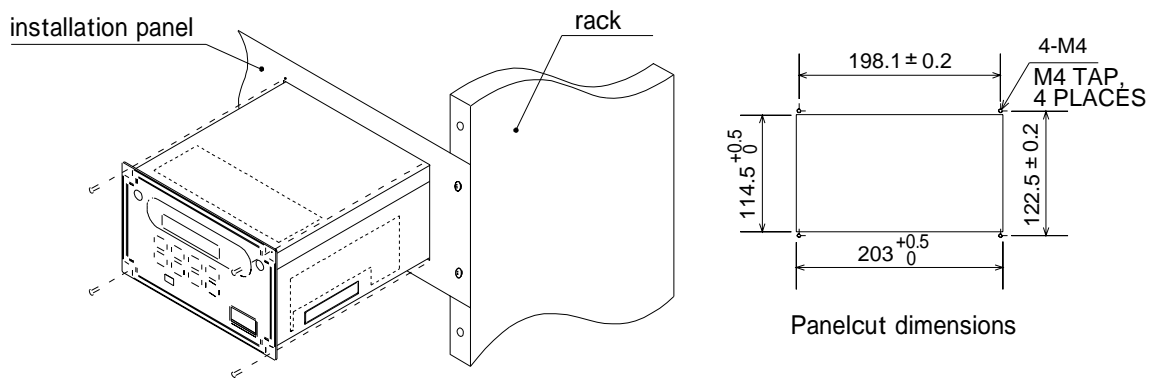


Fig.5-2 Mount the power supply unit

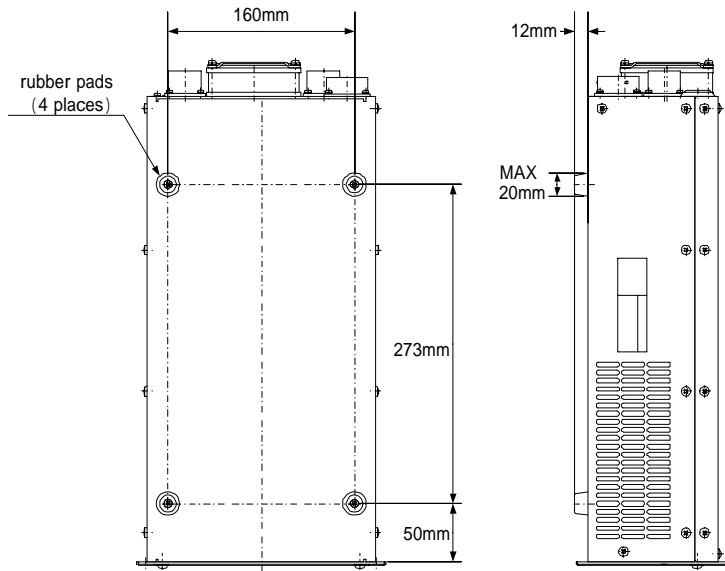


Fig.5-3 Location of rubber pads

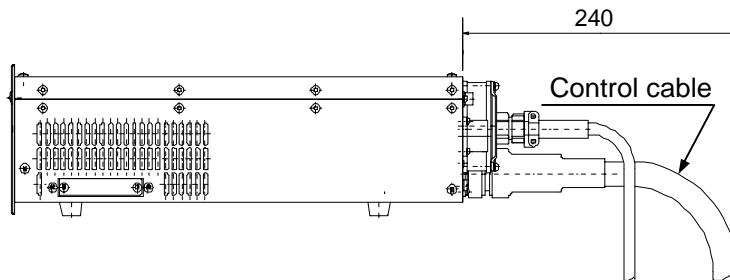


Fig.5-4 Space to connect the cable

5.1.3 Compatibility with Previous Models

If previous EI-xx03M/MD/MZ power supply units (where "xx" is a number that indicates the applicable pump type) are being used installed on a rack, then optional rack mounting kit is required in order to replace these units with EI-Dxx03M power supply units.

The mounting screws are to be supplied by the customer.

Prepare the shelf to support the weight of the power supply unit in the rack.

Optional Parts (Rack Mounting Kit)

	Description	Q'ty	Notes	Parts Number
1	Rack Mounting Panel	1	Steel, painted same color as front panel of power supply unit. (See Fig.5-5)	263-14117
2	Panel Attachment Screws	4	Stainless Steel, M4 L=6mm	

How to install the unit onto the rack :

- (1) Turn the power supply unit over and remove the four rubber pads.
- (2) Attach the rack mounting panel to the power supply unit with four Panel Attachment Screws. (See Fig. 5-6)
- (3) Reattach the rubber pads of the power supply unit if they are necessary.
- (4) Fix to the rack using 4 M4 tap screws. (See Fig. 5-6, Fig. 5-7)

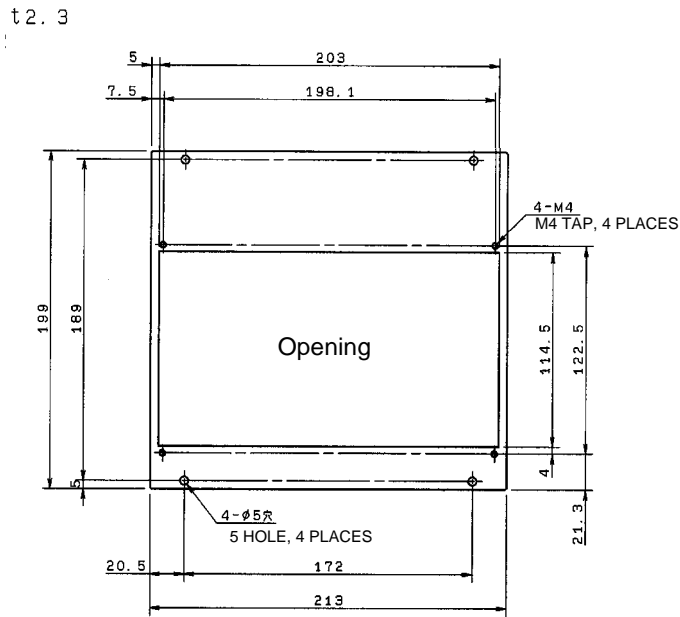


Fig.5-5 Dimensions of Rack Mounting Panel

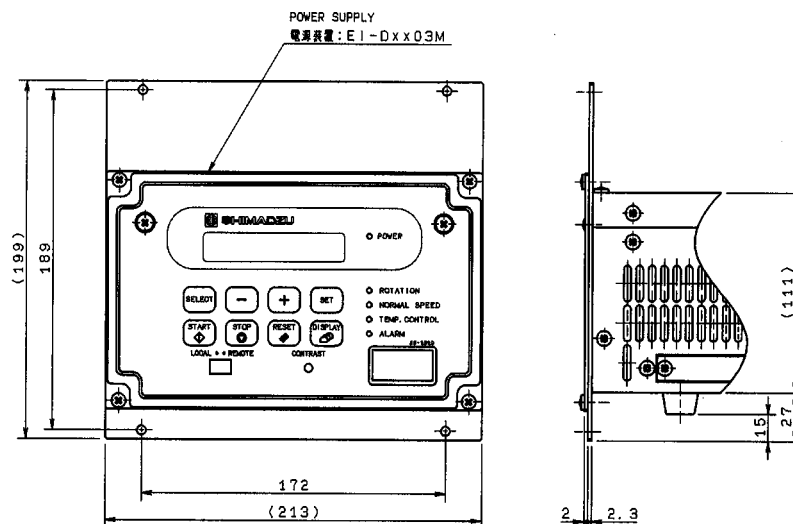


Fig.5-6 Dimensions of the Power Supply Unit with Rack Mounting Panel

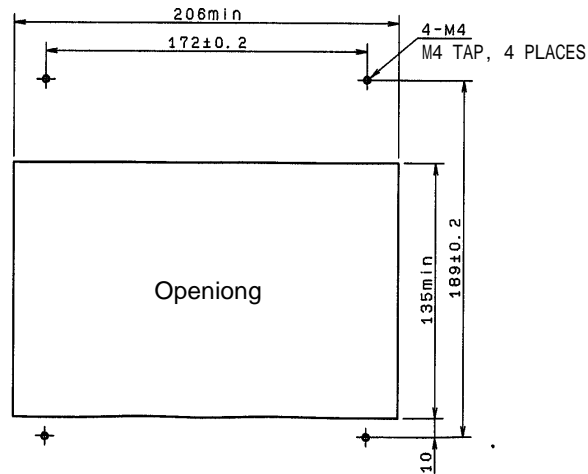


Fig.5-7 Panelcut Dimensions

If a remote-control signal is used, it must be checked for compatibility. For a detailed procedure, please refer to Section 6.7.1 "Compatibility with Previous Models".

5.2 Connection of Power Cable

NOTICE

The power input voltage of the power supply unit EI-Dxx03M (the "xx" number indicates the model of the corresponding pump) is 200 to 240 VAC \pm 10%. Connect the power supply unit to the voltage specified on the rear panel label only. Connection of the power supply unit to the incorrect input voltage can cause damage to the equipment. Supply the power via a breaker (rating 15A). Please provide PE (Protective Earth) connection to the terminal of a "PE" marked wire in final application.

5

Connection of Power Cable:

- (1) Connect the power cable terminal to the terminal board of user's power distribution board for equipment. The wire with [PE] mark is for earth use and other remaining two wires are for single phase AC power. (See Fig. 5-8, Table 5-1)
First, connect the wire [PE] mark. Next connect the other two wires.
- (2) Turn off the POWER switch (Fig. 2-2 (17)) on the rear panel of the power supply unit. Or otherwise be sure to check that it is in off.
- (3) Connect the power cable connectors to the power supply unit AC INPUT connector (Fig. 2-2 (16)).

REFERENCE

For the specified power voltage, see the side panel of the power supply unit.

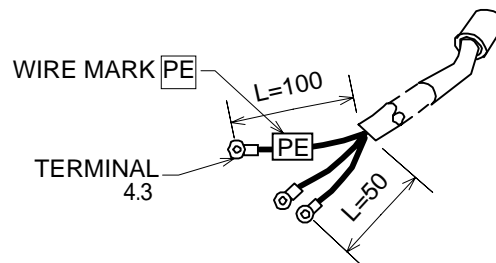


Fig.5-8 Power Cable

Table 5-1 Power Cable CONNECTION

Wire color of power cable		Green/Yellow	Black	White
Location	EU	PE	N	L
	US	GND	L2	L1

5.3 Connection of the Pump to the Power Supply Unit

NOTICE

Insert straight the control cable connector after checking its key direction. Inserting it in oblique direction would cause damage of the connector pins. After the insertion, turn the cable connector clockwise until the rotation lock clicks.

NOTICE

Don't disconnect each cable while the pump is running. Particularly before disconnecting the control cable, Check complete shutdown of the pump by ROTATION lamp goes out and, thereafter, turn off the POWER switch.

Control Cable:

Use the control cable that conformed CE marking. It has ferrite core at power supply side. Control cables available for the use are identified with "262-75369A". But, If no ferrite core is not fixed around a control cable, it is not conformed CE marking.

Check that it is identified as specified. Even the use of other similar cable would disable start-up of the pump, even though it could be connected. After turn on the POWER switch of the power supply unit, ALARM lamp (Fig. 2-1 (14)) lights, if an old type cable is connected.

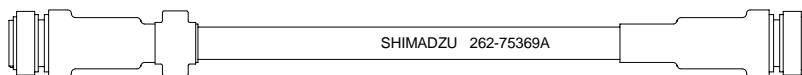


Fig.5-9 Control Cable

Connecting Sequence (See Fig. 2-2 and Fig. 5-10):

- (1) Turn off the POWER switch (Fig. 2-2 (17)) on the rear panel of the power supply unit. Or otherwise check that it is off.
- (2) Connect the power supply unit to the control connector (Fig. 2-2 (19)) of the pump proper with the control cable.
- (3) Connect the power supply unit to the motor connector (Fig. 2-2 (20)) of the pump proper with the motor cable.
- (4) For remote operation of the turbo molecular pump or intake of status signal, etc., connect the RS-485 connector (Fig. 2-2 (21)) or RS-232C connector (Fig. 2-2 (22)), Remote-Control connector (Fig. 2-2 (23)). When using Remote-Control connector, make wiring connection as instructed in Section 6.7 "Remote-Control Connector".

All interfaces are SELV(Safety extra-low Voltage).

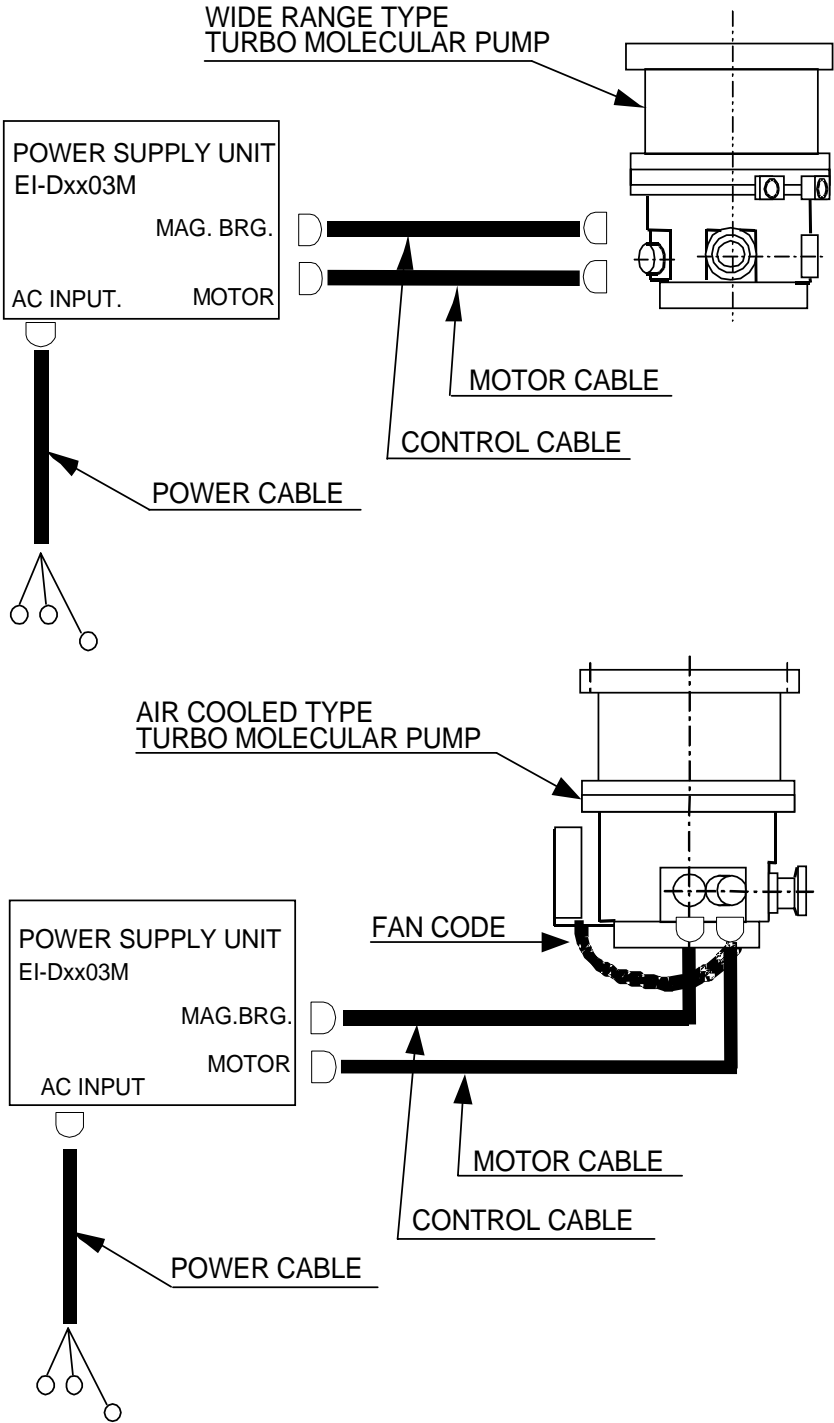


Fig.5-10 Connection of Cables

OPERATION



- 6.1 Outline
 - 6.1.1 Introduction
 - 6.1.2 Operation Flowchart
- 6.2 Start-up Preparation
 - 6.2.1 Start-up Preparation Sequence in LOCAL Mode
 - 6.2.2 Start-up Preparation Sequence in REMOTE Mode
- 6.3 Start-up
 - 6.3.1 Start-up Sequence in LOCAL Mode
 - 6.3.2 Start-up Sequence in REMOTE Mode
- 6.4 Shutting Down
- 6.5 Variable Speed Operation
 - 6.5.1 Outline
 - 6.5.2 Operation from Start-up to Low Speed Rotation
 - 6.5.3 Operation from Rated Speed Rotation to Low Speed Rotation
 - 6.5.4 Operation from Low Speed Rotation to Rated Speed Rotation
- 6.6 Software Operation
- 6.7 Remote-Control Connector
 - 6.7.1 Specifications
 - 6.7.2 Compatibility with Previous Models

6.1 Outline

CAUTION

Neither disconnect and reconnect each cable while the pump is running. Particularly for unplugging the control cable from the receptacle, check complete shutdown of the pump by ROTATION lamp goes out and, thereafter, turn off the POWER switch.

CAUTION

Do not turn the power off while the pump is running. The touch-down bearing may need to be replaced if the power is turned off repeatedly during operation. When the power is turned off while the pump is rotating, power from regenerative braking maintains the magnetic levitation until the rotational speed drops. Levitation then stops and the touch-down bearing supports the rotor. Consequently, repeated touch-down operations can reduce the life of the bearing.

6.1.1 Introduction

(See Fig. 2-1 and Fig. 2-2)

The LCD (Fig. 2-1 (1)) displays the model name of the power supply unit corresponding to the pump model name (e.g. SHIMADZU EI-Dxx03M) when the power supply unit POWER switch (Fig. 2-2 (17)) is turned on.

It then displays "SELF CHECKING" and the power supply unit conducts self-diagnosis. If the result is good, the LCD changes into monitor mode (See section 6.6 Software Operation (1)), and the power supply is operatable. But if an alarm is detected, the LCD changes into alarm mode (See Section 6.6 Software Operation (2)), and displays detected alarm.

6.1.2 Operation Flowchart

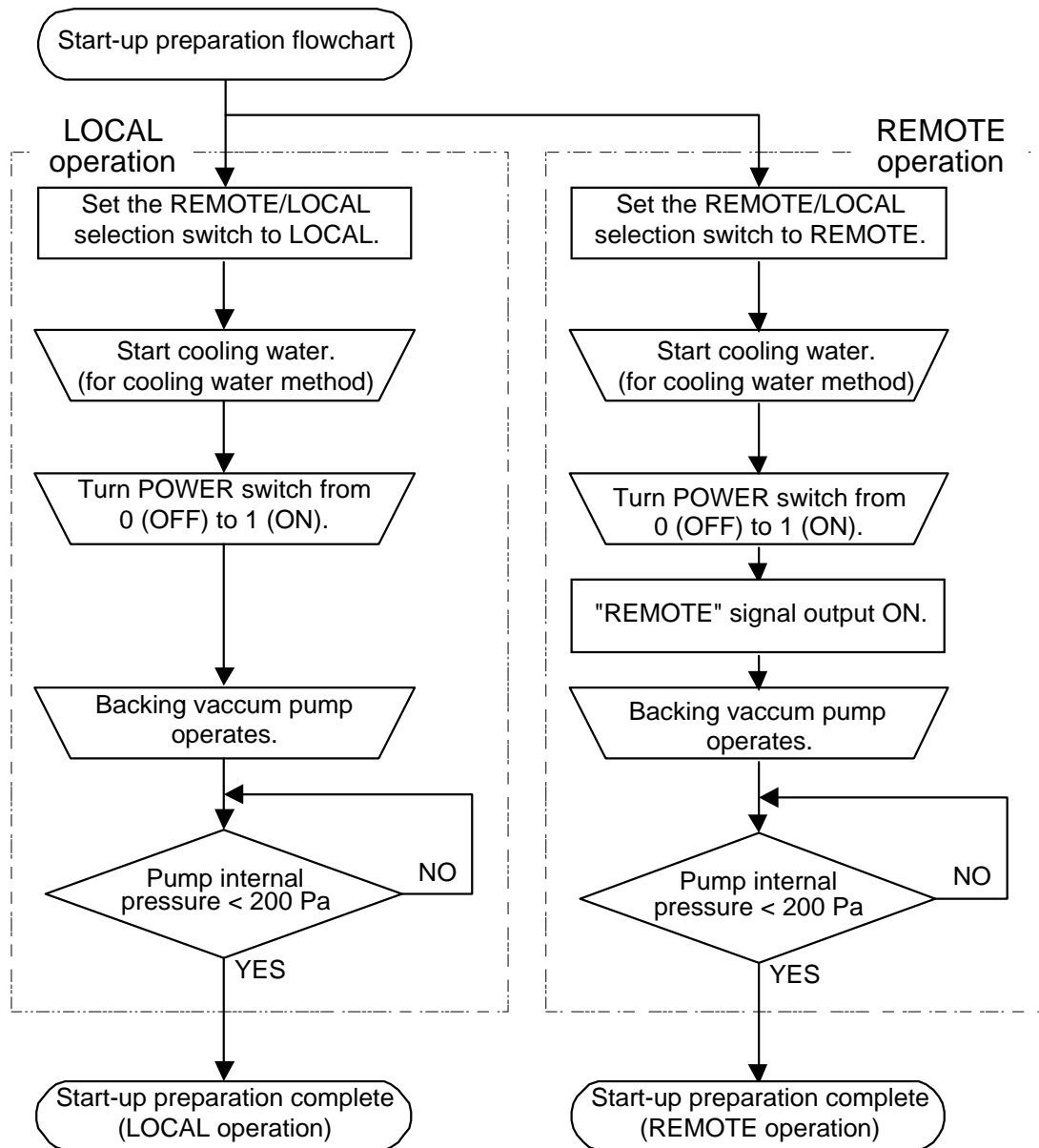


Fig. 6-1 Start-up Preparation Flowchart

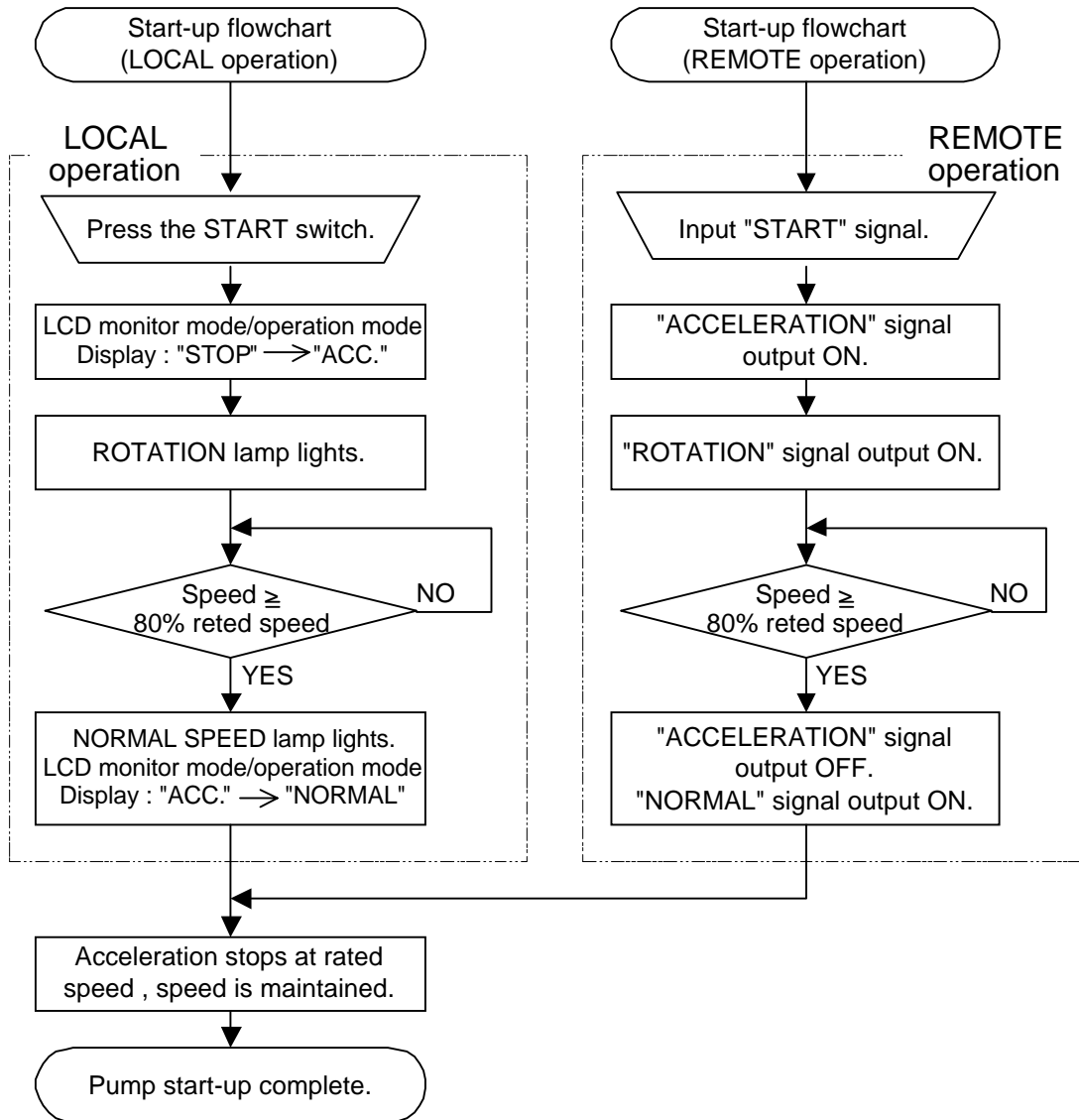


Fig. 6-2 Start-up Flowchart

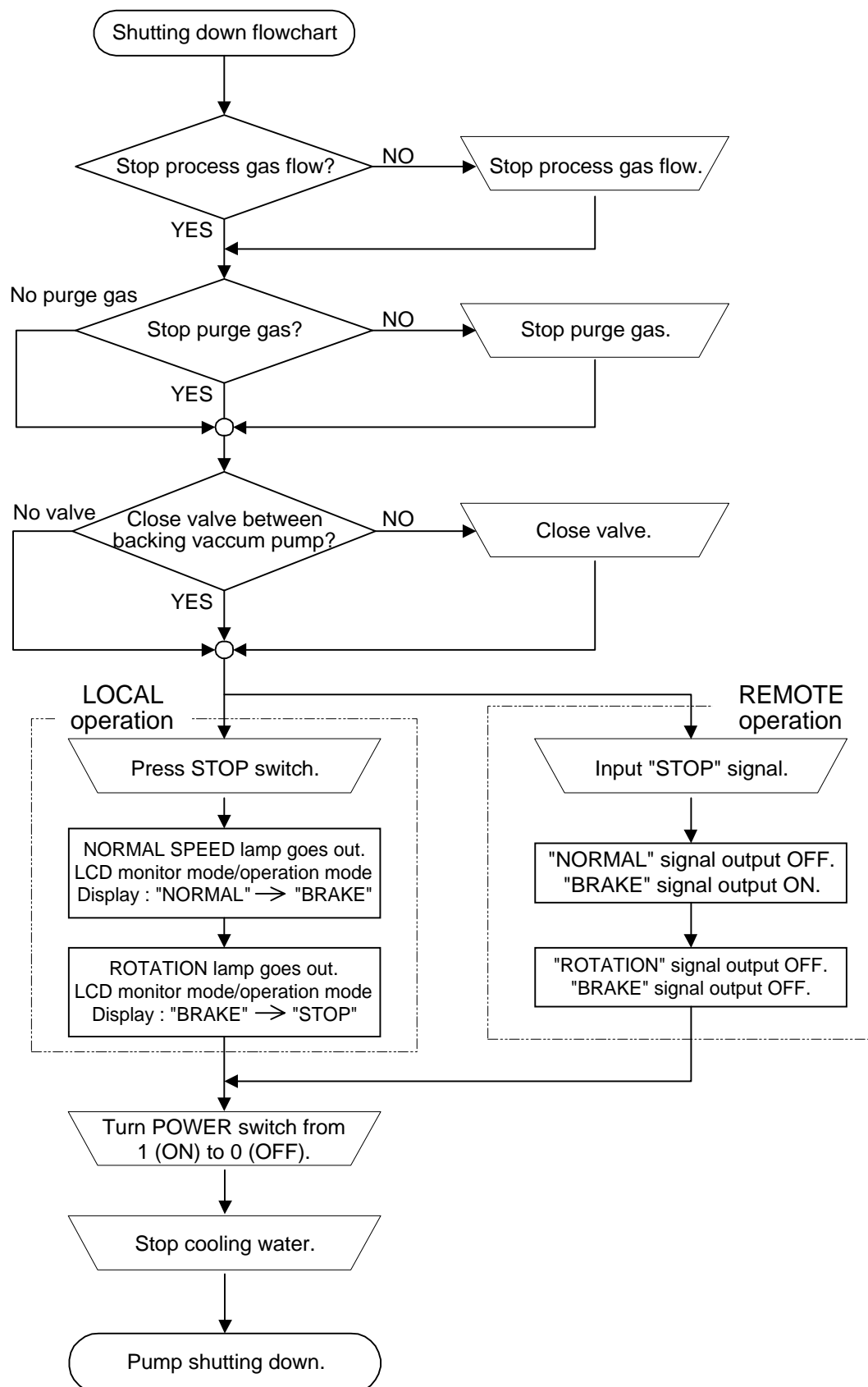
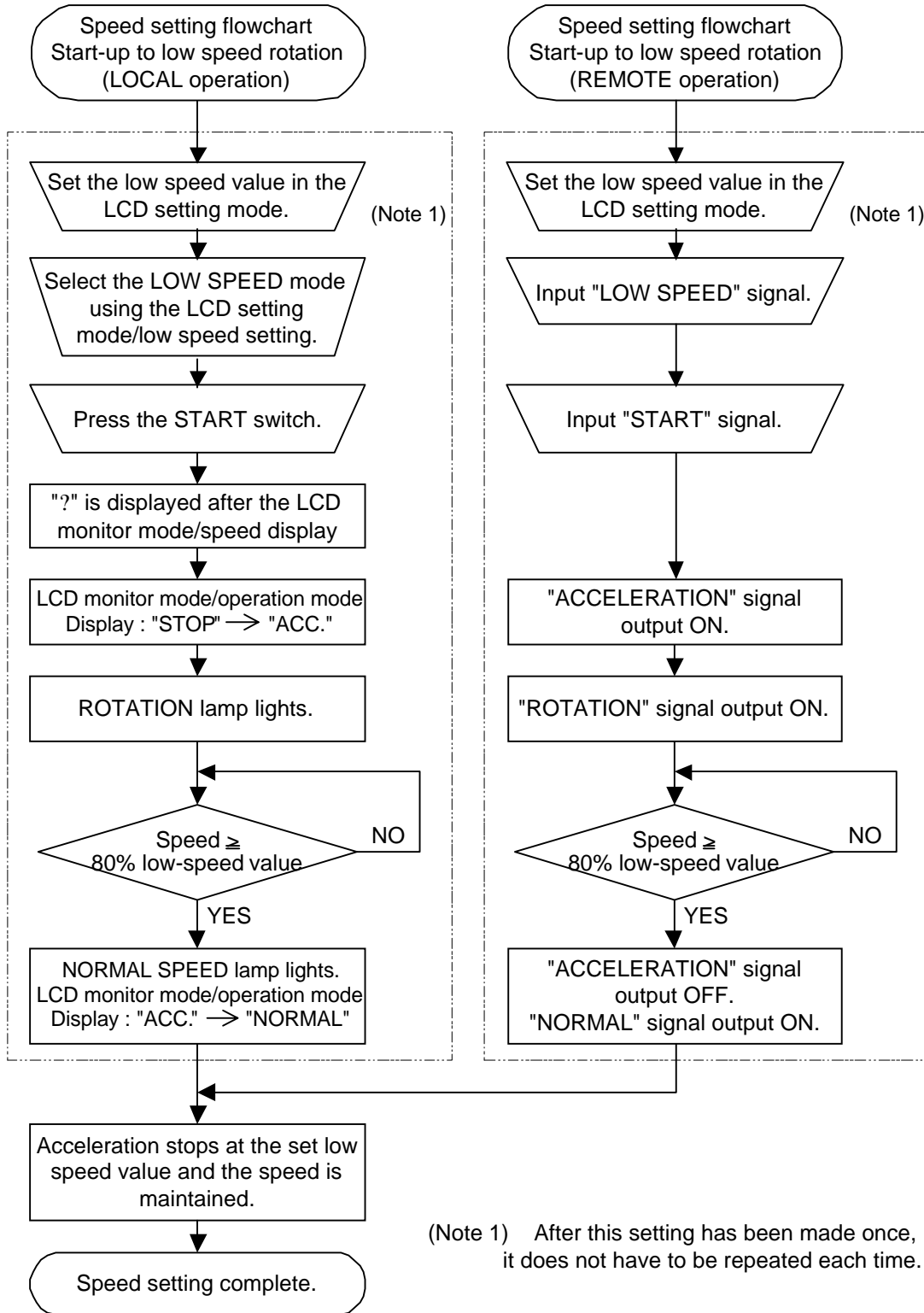
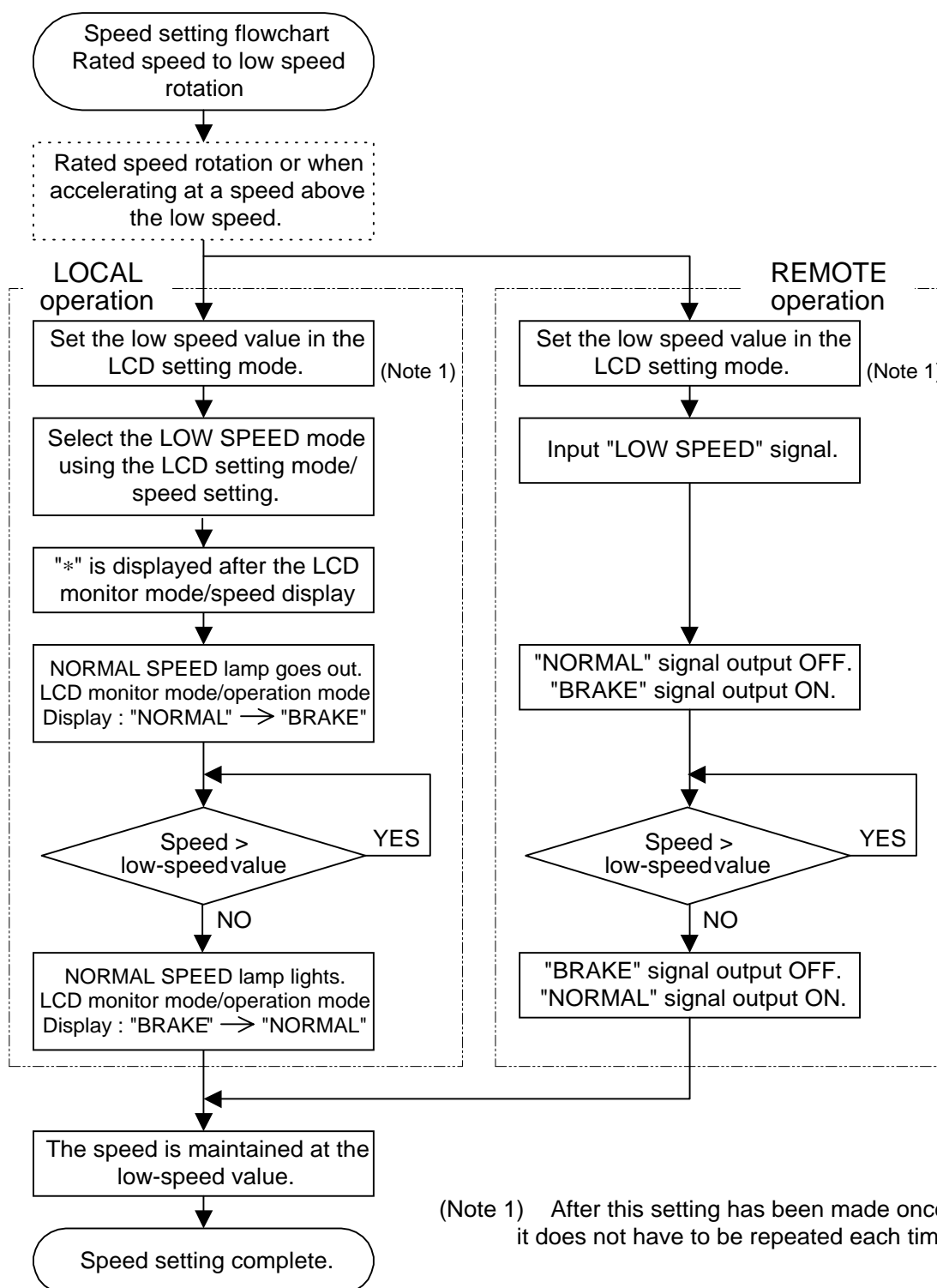
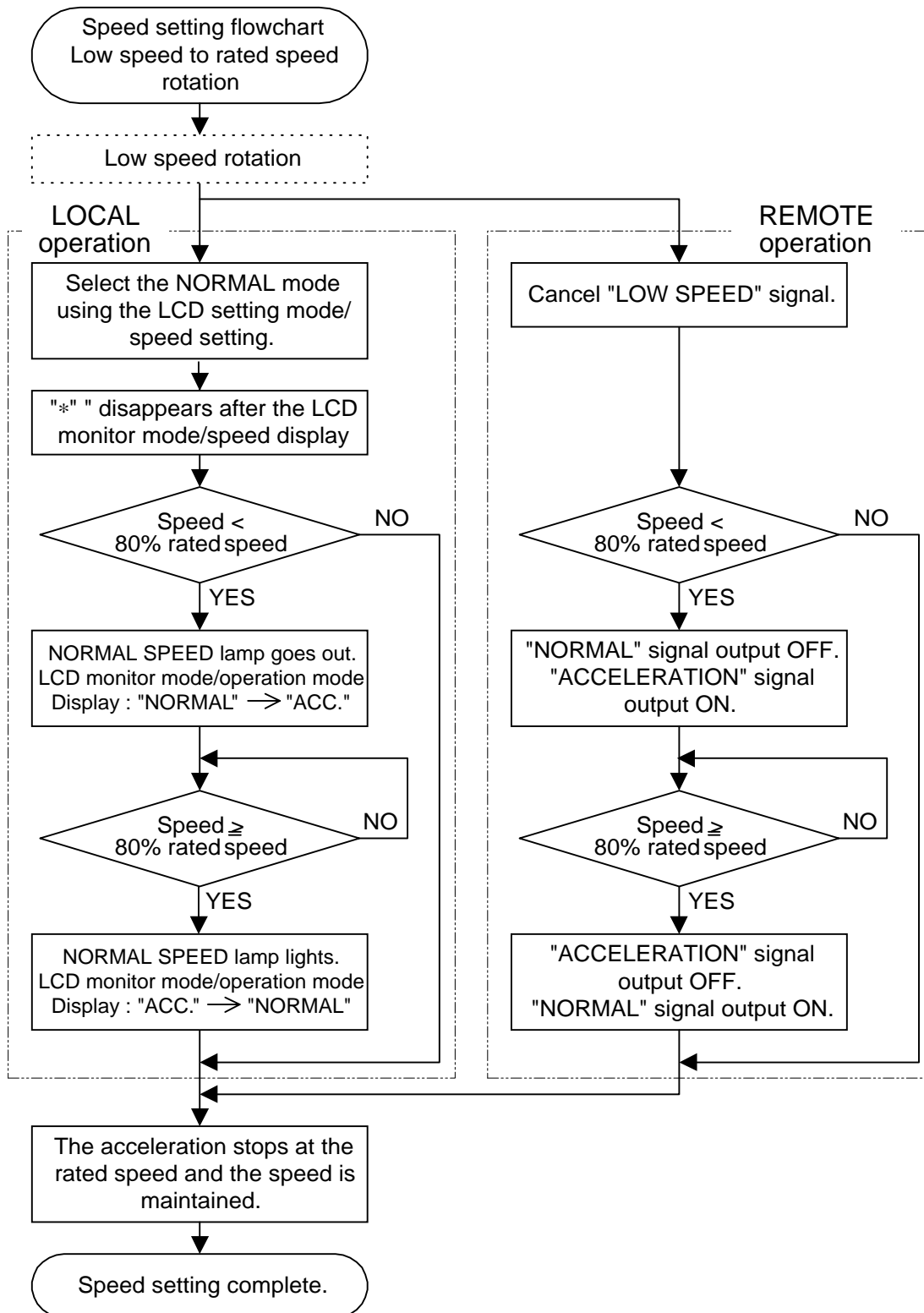


Fig. 6-3 Shutting down Flowchart



Start-up to Low Speed Rotation
Fig. 6-4 Speed Setting Flowchart

**Rated Speed to Low Speed Rotation****Fig. 6-5 Speed Setting Flowchart**



Low Speed to Rated Speed Rotation
Fig. 6-6 Speed Setting Flowchart

6.2 Start-up Preparation

Shift the REMOTE/LOCAL selection switch (Fig. 2-1 (15)) to either LOCAL or REMOTE mode.

LOCAL	The pump can be started/stopped by pressing START/STOP switch on the front panel of the power supply unit.
REMOTE	the pump runs only according to input signal from the remote-control connector (Fig. 2-2 (23)) or serial interface connector (Fig. 2-2 (21), (22)).

See APPENDIX-A "COMMUNICATIONS" for serial interface connector.

6

6.2.1 Start-up Preparation Sequence in LOCAL Mode

- (1) Feed the cooling water into the cooling line. (for cooling water method)
- (2) Turn on the POWER switch (Fig. 2-2 (17)) of the power supply unit and check if the POWER lamp (Fig. 2-1 (10)) lights. And the rotor of the turbo molecular pump is levitated by the magnetic bearing.
- (3) Evacuate the turbo molecular pump by using a backing vacuum pump.
- (4) Start-up preparation is complete if the pressure in the turbo molecular pump reduces below 200 Pa.

6.2.2 Start-up Preparation Sequence in REMOTE Mode

- (1) Feed the cooling water into the cooling line. (for cooling water method)
- (2) Turn on the POWER switch (Fig. 2-2 (17)) of the power supply unit and check that "REMOTE" signal (see Table 6-3) from the remote-control connector (Fig. 2-2 (23)) is ON. Under this condition, the rotor of the turbo molecular pump is levitated by the magnetic bearing.
- (3) Evacuate the turbo molecular pump by using a backing vacuum pump.
- (4) Start-up preparation is complete if the pressure in the turbo molecular pump reduces below 200 Pa.

NOTICE

When turning the POWER switch for the power supply unit on or off, a "clunk" sound may be heard from inside the pump. This sound is from the rotor inside the pump being levitated or de-levitated. This is normal.

6.3 Start-up

6.3.1 Start-up Sequence in LOCAL Mode

- (1) Start-up begins when the 6.2.1 "Start-up Preparation Sequence in LOCAL Mode" is complete.
- (2) Press START switch (Fig. 2-1 (6)).
- (3) ACC." is displayed on the pump monitor mode/operation mode LCD and pump acceleration starts. After a few seconds, the ROTATION lamp (Fig. 2-1 (11)) lights.
- (4) When the rotational speed reaches 80% rated value, the NORMAL SPEED lamp (Fig. 2-1 (12)) lights and the pump monitor mode/operation mode LCD changes from ACC. to NORMAL. Pump start-up is complete.

6.3.2 Start-up Sequence in REMOTE Mode

- (1) Start-up begins when the 6.2.2 "Start-up Preparation Sequence in REMOTE Mode" is complete.
- (2) START" signal (see Table 6-3) is input from the remote-control connector (Fig. 2-2 (24)).
- (3) The pump acceleration starts when the remote-control connector "ACCELERATION" signal (see Table 6-3) turns ON. After a few seconds the "ROTATION" signal (see Table 6-3) turns ON.
- (4) When the rotational speed reaches 80% rated value, the remote-control connector "ACCELERATION" signal (see Table 6-3) turns OFF and the "NORMAL" signal (see Table 6-3) turns ON. Pump start-up is complete.

6.4 Shutting Down

CAUTION

After having operated the turbo molecular pump for evacuation of corrosive gas, keep the pump internal as vacuumed even after shutdown. Inflow of water content in the air to the pump internal would cause rapid corrosion trouble of the pump internals. The pump corrosion may result in damaging the vacuum vessel interior and other units, causing pressure fluctuation by stopping the pump and dispersal of parts.

CAUTION

When reducing internal pressure of the turbo molecular pump up to around the atmospheric pressure by use of inert gas, etc., adjust the pressure reducing valve so that the internal pressure of the same pump does not exceed 20 kPa [GAUGE].

For shut-down of the turbo molecular pump, follow the sequence below.

6.4.1 Preparations Prior to Shutting Down Operation

- (1) Check that process gas inflow is in complete stop. When main valve is provided between the turbo molecular pump and vacuum chamber, close the valve, too.
- (2) When purge gas is being fed into the turbo molecular pump, stop the gas feed, too.
- (3) When forevacuum valve is provided between the turbo molecular pump and backing vacuum pump, close the valve, too.

6.4.2 Shutting Down Sequence in LOCAL Mode

- (1) Press the STOP switch (Fig. 2-1 (7)) and check that the indication on the pump monitor mode/operation mode LCD switches from "NORMAL" to "BRAKE."
Then the NORMAL SPEED lamp (Fig. 2-1 (12)) goes off.
- (2) Wait until the ROTATION lamp (Fig. 2-1 (11)) goes out. The pump monitor mode/operation mode LCD switches from "BRAKE" to "STOP."
- (3) Turn off the power supply unit POWER switch (Fig. 2-2 (17)).
- (4) Stop the cooling water flow.

6.4.3 Shutting Down Sequence in REMOTE Mode

- (1) Input the "STOP" signal (see Table 6-3) from the remote-control connector (Fig. 2-2 (24)) and check that the "BRAKE" signal (see Table 6-3) is ON.
- (2) Wait until the "ROTATION" signal (see Table 6-3) turns OFF. At this time, the "BRAKE" signal (see Table 6-3) also turns OFF.
- (3) Turn off the power supply unit POWER switch (Fig. 2-2 (17)).
- (4) Stop the cooling water flow.

6

When the turbo molecular pump is turned off after pumping a corrosive gas, maintain a vacuum inside the turbo molecular pump or purge the interior of the pump with an inert gas.

Further, in such a case when a hydraulic rotary vacuum pump is used as backing vacuum pump and there is possible reverse flow and diffusion of oil from the backing vacuum pump, return the pump internal pressure to atmospheric pressure using dry nitrogen gas, after complete shut-down of the pump [ROTATION lamp (Fig. 2-1 (11)) goes out], to prevent the turbo molecular pump from being contaminated with oil vapor.

For shutting down the turbo molecular pump in running at high speed with infeed of dry nitrogen gas to the pump, keep the nitrogen gas flow rate at 1500 mL/min maximum.

REFERENCE

ROTATION lamp (Fig. 2-1 (11)) goes out or "ROTATION" signal (see Table 6-3) turns off when the pump rotational speed is 60rpm or less. Turning off the POWER switch (Fig. 2-2 (17)) permits the pump rotor to be supported by the touch-down bearings.

6.5 Variable Speed Operation

CAUTION

When using the variable speed function to change the pump rotation rate, use a rotation rate that does not cause resonance with other devices installed at the site.

6

CAUTION

If an EI-Dxx03M power supply unit is used in combination with an existing pump that was operated in combination with a power supply unit not having the variable speed function (EI-xx03MD), the variable speed function cannot be used. (the "xx" number indicates the model of the corresponding pump.)

If the power supply unit is to be combined with an existing pump, modification and operational inspections are necessary. Please contact Shimadzu for detailed information.

6.5.1 Outline

- (1) The rotational speed settings function sets the rotational speed by selecting between the NORMAL speed mode or LOW SPEED mode.
- (2) Select the NORMAL mode or LOW SPEED mode by LOCAL operation using the setting mode/rotational speed settings/speed setting set value on the LCD display or by REMOTE operation using the remote-control connector "LOW SPEED" signal input (see Table 6-3).
- (3) The NORMAL mode or LOW SPEED mode selection can be made before or after start-up. (See the Speed Setting Flowcharts in Figs. 6-4, 6-5, and 6-6.)
- (4) Set the low speed value between 25% and 100% of the rated speed in 0.1% increment with the setting mode/rotational speed settings/low speed setting set value on the LCD display.
- (5) The low speed value can be set while the pump is rotating in the LOW SPEED mode. The pump then accelerates or decelerates to the new set value and maintains the set speed.
- (6) The time required for the speed to change is the same as the time for normal acceleration or deceleration.

For example, if the low speed value is set to 80% and the LOW SPEED mode is selected during normal rotation, the time for the speed to drop to 80% is approximately one-fifth the time required to stop from rated speed.

6.5.2 Operation from Start-up to Low Speed Rotation

This is the procedure until low-speed rotation is achieved when the speed setting is made with the pump stopped.

LOCAL Operation

- (1) Start-up begins when the 6.2.1 "Start-up Preparation Sequence in LOCAL Mode" is complete.
- (2) Set the low speed value with the setting mode/rotational speed settings/low speed setting set value on the LCD display. (See Section 6.6 "Software Operation" (4).) After this setting has been made once, it does not have to be repeated each time.
- (3) Select the LOW SPEED mode using the setting mode/rotational speed settings/low speed setting set value. (See Section 6.6 "Software Operation" (4).)
- (4) Press the START switch (Fig. 2-1 (6)).
- (5) While the speed is changing, "*" is displayed after the monitor mode/speed display. (See Section 6.6 "Software Operation" (1).)
- (6) ACC is displayed on the pump monitor mode/operation mode LCD and the pump starts to accelerate. After a few seconds the ROTATION lamp (Fig. 2-1 (11)) lights.
- (7) When the rotational speed reaches 80% of low-speed value, the NORMAL SPEED lamp lights (Fig. 2-1 (12)) and the pump monitor mode/operation mode LCD switches from "ACC." to "NORMAL".
- (8) When the pump speed reaches the set low speed value, acceleration stops and the pump speed is maintained.

The same operation occurs if the LOW SPEED mode is selected after the START switch is pressed but before the pump speed reaches the set low speed value.

REMOTE Operation

- (1) Start-up begins when the 6.2.2 "Start-up Preparation Sequence in REMOTE Mode" is complete.
- (2) Set the low speed value with the setting mode/rotational speed settings/low speed setting set value on the LCD display. (See Section 6.6 "Software Operation" (4).) After this setting has been made once, it does not have to be repeated each time.
- (3) Input the "LOW SPEED" signal (see Table 6-3) from the remote-control connector (Fig. 2-2 (23)).
- (4) Input the "START" signal from the remote-control connector (Table 6-3).
- (5) The pump starts to accelerate when the "ACCELERATION" signal (see Table 6-3) from the remote-control connector (Fig. 2-2 (23)) turns ON. After a few seconds the "ROTATION" signal turns ON.
- (6) When the rotational speed reaches 80% of low speed value, the remote-control connector "ACCELERATION" signal turns OFF and the "NORMAL" signal turns ON.
- (7) When the pump speed reaches the set low speed value, acceleration stops and the pump speed is maintained.

The same operation occurs if the "LOW SPEED" signal is input after the "START" signal is input but before the pump speed reaches the set low speed value.

6.5.3 Operation from Rated Speed Rotation to Low Speed Rotation

This is the procedure to select low speed operation during rated speed rotation or when accelerating at a speed above the low speed.(see Fig. 6-5)

LOCAL Operation

- (1) Set the low speed value with the setting mode/rotational speed settings/low speed setting set value on the LCD display. (See Section 6.6 "Software Operation" (4).) After this setting has been made once, it does not have to be repeated each time.
- (2) Next, select the LOW SPEED mode using the setting mode/rotational speed settings/speed setting set value on the LCD display. (See Section 6.6 "Software Operation" (4).)
- (3) While the speed is changing, "*" is displayed after the monitor mode/speed display. (See Section 6.6 "Software Operation" (1).)
- (4) The pump monitor mode/operation mode LCD switches from "NORMAL" to "BRAKE" and the pump starts to decelerate. Then the NORMAL SPEED lamp (Fig. 2-1 (12)) goes off.
- (5) When the rotational speed reaches the set low speed value, the NORMAL SPEED lamp lights and the pump monitor mode/operation mode LCD switches from "BRAKE" to "NORMAL."
- (6) The pump stops decelerating and the pump speed is maintained.

A normal start-up and normal operation occurs if the mode is reverted to NORMAL speed before the pump speed reaches the set low speed value.

REMOTE Operation

- (1) Set the low speed value with the setting mode/rotational speed settings/low speed setting set value on the LCD display. (See Section 6.6 "Software Operation" (4).) After this setting has been made once, it does not have to be repeated each time.
- (2) Input the "LOW SPEED" signal (see Table 6-3) from the remote-control connector (Fig. 2-2 (23)).
- (3) The pump starts to decelerate when the remote-control connector "NORMAL" signal (see Table 6-3) turns OFF and the "BRAKE" signal (see table 6-3) turns ON.
- (4) When the pump speed reaches the set low speed value, the remote-control connector "BRAKE" signal turns OFF and the "NORMAL" signal turns ON.
- (5) The pump stops decelerating and the pump speed is maintained.

A normal start-up and normal operation occurs if the "LOW SPEED" signal is cancelled before the pump speed reaches the set low speed value.

6.5.4 Operation from Low Speed Rotation to Rated Speed Rotation

This is the procedure to select normal speed operation during low speed rotation.
(see Fig. 6-6)

LOCAL Operation

- (1) Select the NORMAL mode using the setting mode/rotational speed settings/speed setting set value on the LCD display. (See Section 6.6 "Software Operation" (4).)
- (2) The "*" disappears after the monitor mode/speed display. (See Section 6.6 "Software Operation" (1).)
- (3) If the set low speed value did not exceed 80% rated speed, the pump monitor mode/operation mode LCD switches from "NORMAL" to "ACC." and the pump starts to accelerate. The NORMAL SPEED lamp (Fig. 2-1 (12)) goes off.

When the rotational speed reaches 80% rated speed, the NORMAL SPEED lamp lights and the pump monitor mode/operation mode LCD switches from "ACC." to "NORMAL."

- (4) If the set low speed value exceed 80% rated speed, the LCD display remains unchanged and the pump accelerates.
- (5) When the rated speed is reached, the pump stops accelerating and the pump speed is maintained.

REMOTE Operation

- (1) Cancel the "LOW SPEED" signal (See table 6-3) inputted in the remote-control connector (Fig. 2-2 (23)).
- (2) If the set low speed value did not exceed 80% rated speed, the remote-control connector "ACCELERATION" signal turns ON and (see Table 6-3) and the pump starts to accelerate. The "NORMAL" signal turns OFF. When the rotational speed reaches 80% rated speed, the remote-control connector "ACCELERATION" signal turns OFF and the "NORMAL" signal turns ON (see Table 6-3).
- (3) If the set low speed value exceed 80% rated speed, remote-control signals remain unchanged and the pump accelerates.
- (4) When the rated speed is reached, the pump stops accelerating and the pump speed is maintained.

6.6 Software Operation

The software operation functions are listed in Table 6-1.

Table 6-1 Software Operation Functions

Function	Description	Reference flowchart	
Operation mode User memo Operation status Motor speed Motor current Magnetic bearing monitor (Note 1)	Monitors pump operation status	(1) Monitor mode	
Alarm and warning display	Displays details of alarms and warnings.	(2) Alarm mode	
Alarm and warning history and details	Display the alarm and warning history.		
Run time Maintenance call time Number of power failure touch-downs Number of high-speed touch-downs Number of magnetic bearing warnings	Resets times and counters.	(3) Menu mode	Timer
User memo setting	Inputs user memo.		Setting
RS-232C setting	Sets the communication environment.		
RS-485 setting	Sets the communication environment.		
Speed setting	Sets the pump speed display format.		
Remote-control signal setting	Sets the operations of the remote-control signals.		
Default setting	Reverts to the default settings.		

(Note 1) When during the low speed rotation (less than 50% of rated speed), or detected alarm below, the monitor function do not operate.

Alarm code:46,47(rotational speed error), 51 to 55(excessive vibration of the magnetic bearing), 66(magnetic bearing control error), 68,69(rotor is out of balance)
(see Table 10-5)

A flowchart of the entire LCD display is shown below.

SELECT, +, -, SET in the flowchart indicate keys on the power supply unit front panel represent the LCD display.

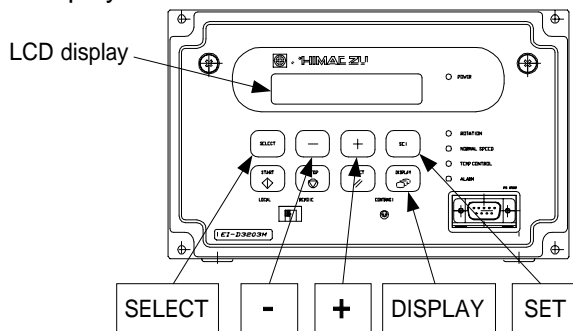
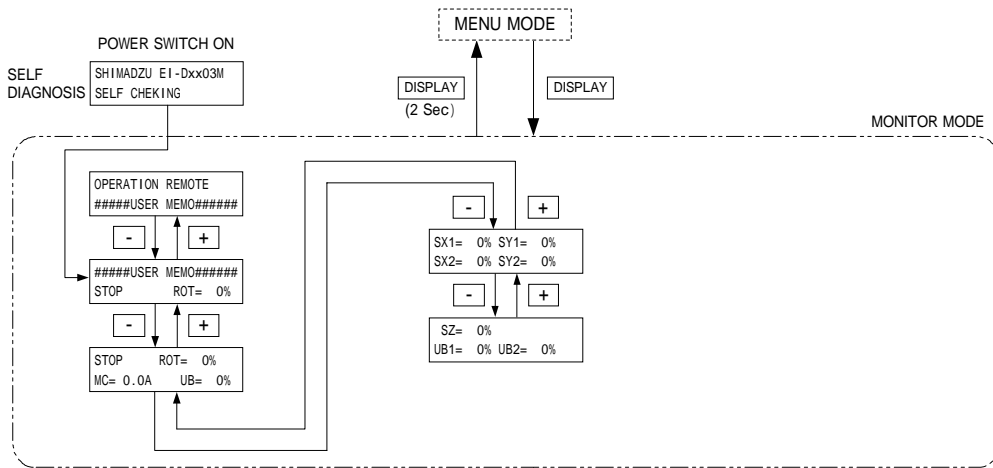
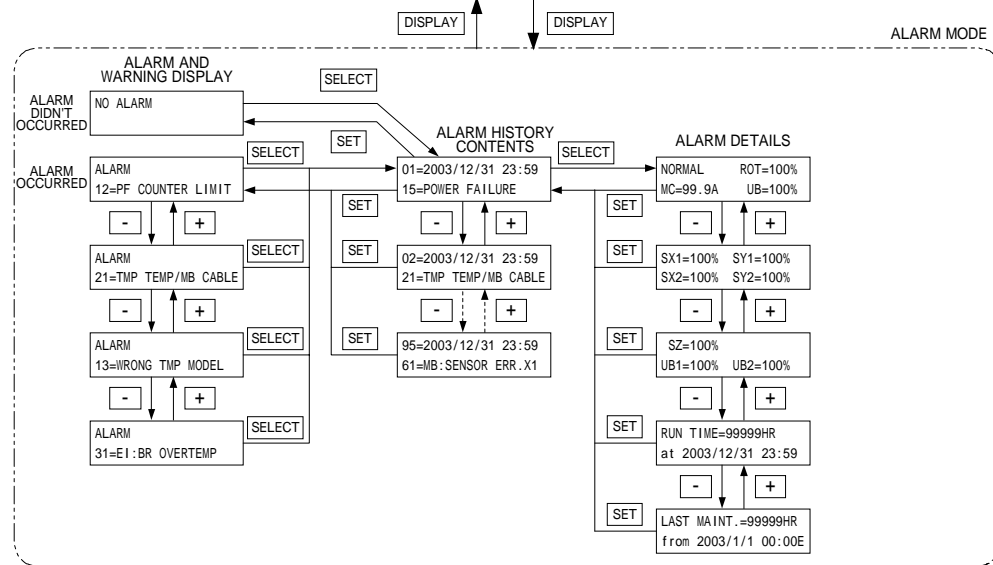


Fig. 6-7 Power Supply Unit Front Panel

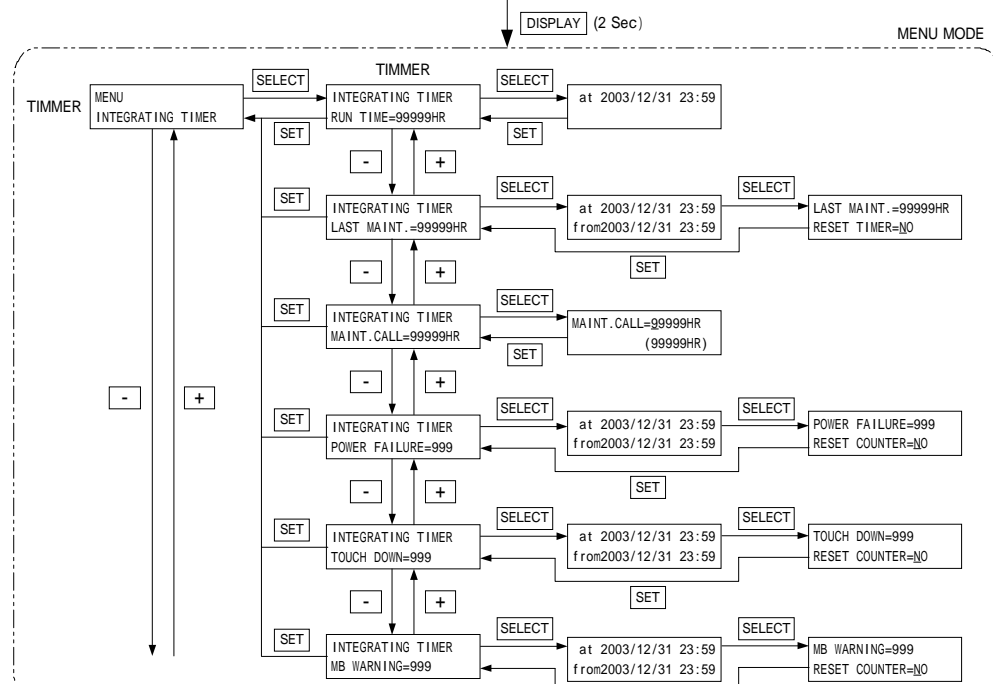
SECTION 6 OPERATION



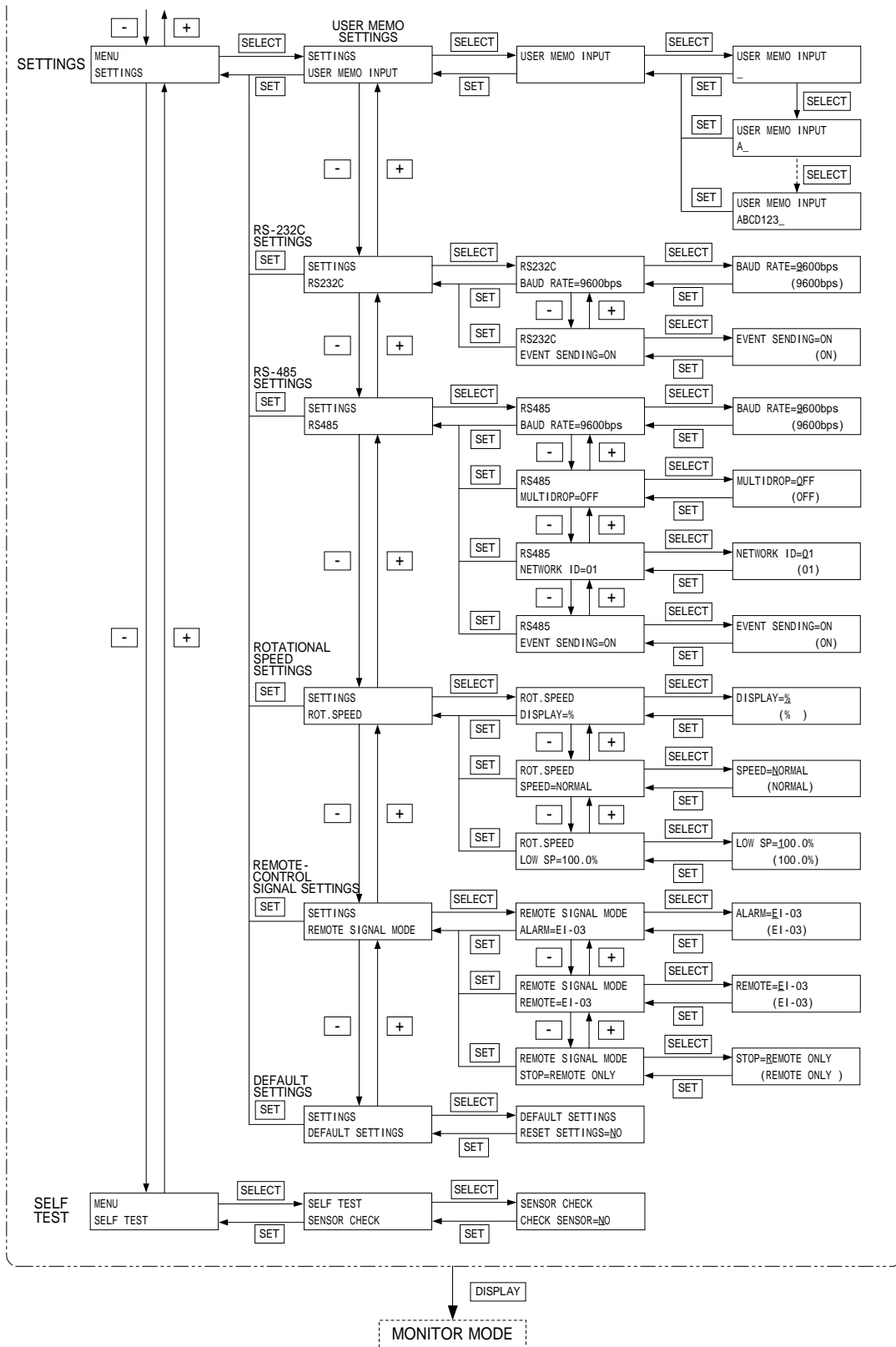
Detail P46



Detail P47



Detail P48



SECTION 6 OPERATION

In the next tables, they are shown detailed flowchart of LCD display.

(1) MONITOR MODE

In monitor mode operation status of pump can be identified. If key **DISPLAY** is pushed in menu mode, the LCD changes into monitor mode. The LCD changes automatically into monitor mode after start or stop operation.

Mode	Operation and LCD Display	Description of Display
MONITOR 1		
MONITOR 2		
MONITOR 3		
MONITOR 4		
MONITOR 5		

First, Monitor 2 display following to initial display after power switch turning on.

(Note 1) Operation Mode

LCD Display	Operation
LOCAL	Control by a manual switch operation on the front panel
REMOTE	Control by a remote-control signal operation
RS-232C	Control by a RS-232C communication
RS-485	Control by a RS-485 communication

Refer to Section 6.2 for details on changing the operation mode.

(Note 2) Pump Operation Mode

LCD Display	Pump Operation
NORMAL	Normal rotation
ACC.	Motor acceleration
BRAKE	Motor brake deceleration
STOP	Motor stop
IDLE	Free operation
E-STOP	Error occurs (stop)
E-BRAKE	Error occurs (motor deceleration)
E-IDLE	Error occurs (free operation = motor stop)

(Note 3) Any character can be entered in the USER MEMO from the menu mode "SETTINGS/ USER MEMO INPUT". Use it for displaying the chambers connected to the pump etc.

(Note 4) The Motor Rotational Speed display can be selected from %, rpm and rps in the menu mode "SETTINGS/ ROT.SPEED/ DISPLAY".

An asterisk (*) is displayed after the speed display during variable speed operation.

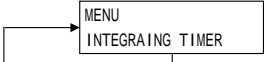
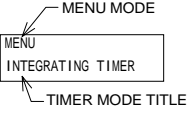
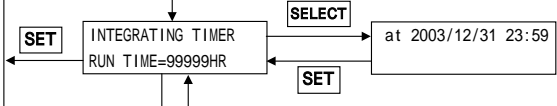
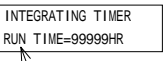
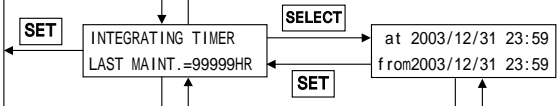
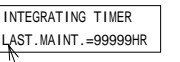

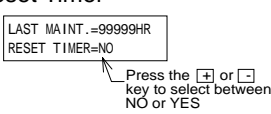
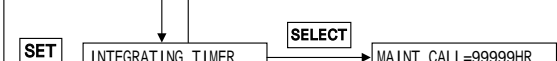
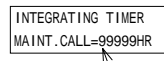
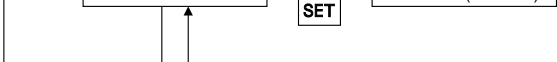
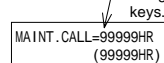
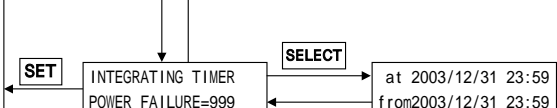
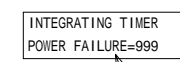
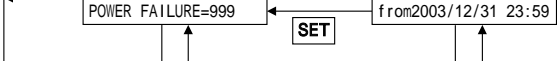
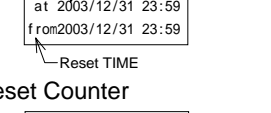
SECTION 6 OPERATION

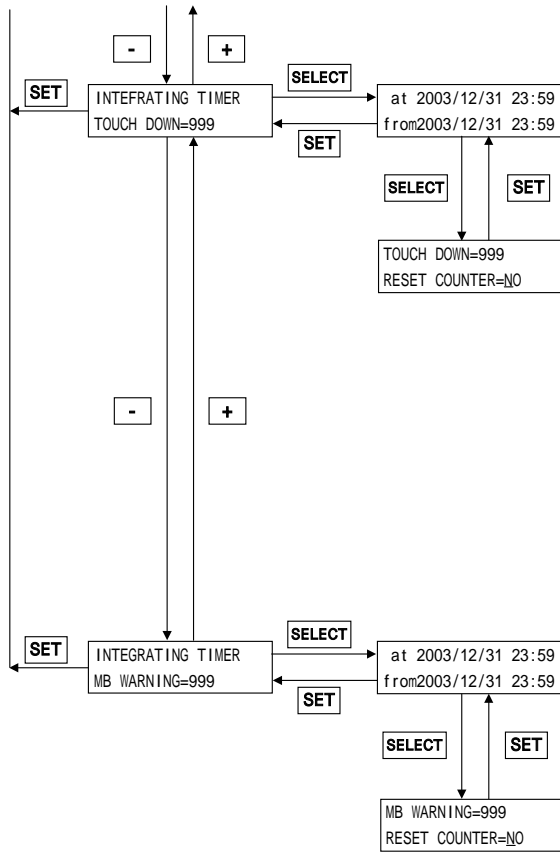
(2) ALARM MODE

Alarm mode is a mode to display detected alarm contents and alarm history. If key **DISPLAY** is pushed in monitor mode, the LCD changes into alarm mode. The LCD changes automatically changes into alarm mode when an alarm is detected. See Table 10-5 "Table of Alarms" and Table 10-6 "Table of Warnings" about alarm code.

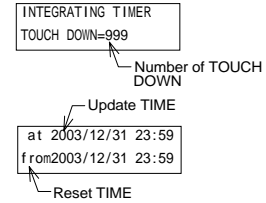
Mode	Operation and LCD Display	Description of Display
ALARM LIST		<p>The currently detected error is displayed. If there is more than one error, all the errors can be displayed using the + and - keys.</p> <p>ALARM No.1</p> <p>ALARM No.2</p> <p>ALARM No.3</p>
ALARM HISTORY		<p>Maximum ALARM No.99</p> <p>HISTORY No.</p>
ALARM HISTORY DETAILS		<p>The pump's operating status when an error is detected is displayed.</p> <p>Pump Operation Mode</p> <p>Motor Rotational Speed</p> <p>Motor Current</p> <p>Unbalance Monitor Value</p> <p>Magnetic Bearing Sensor Input Value X1,Y2,X2,Y2 Axis</p> <p>Magnetic Bearing Sensor Input Value Z Axis</p> <p>Run time</p> <p>Maintenance call time</p> <p>Reset TIME</p>

(3) MENU MODE/TIMER

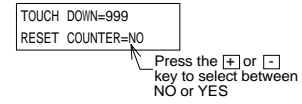
Mode	Operation and LCD Display	Description of Display
MENU		
INTEGRATING TIMER		<p>The pump's integrated run time is displayed.</p> 
INTEGRATING TIMER		<p>The pump's integrated run time is displayed. Reset is possible at the same time as, for example, maintenance.</p> 
INTEGRATING TIMER		<p>Select Reset Timer</p> 
INTEGRATING TIMER		<p>If the integrated value for the maintenance call time exceeds the set value, alarm code 99 (maintenance call warning) occurs. Setting the set value to 0 disables this function.</p> 
INTEGRATING TIMER		
INTEGRATING TIMER		<p>A cursor moves to the right when pushes SELECT key.</p> <p>The number of power failure touch-downs is counted. If this number exceeds 250, alarm code 12 (number of power failure touch-downs alarm) occurs. Refer to Table 7-4 for the appropriate remedy.</p> 
INTEGRATING TIMER		<p>Select Reset Counter</p> 



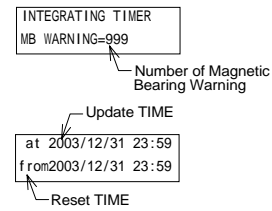
The number of alarms that occur for the magnetic bearing system at speeds exceeding 80% of the rated speed is counted. If this number exceeds 10, alarm code 11 (number of high-speed touch-downs alarm) occurs.



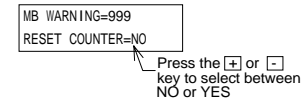
Select Reset Counter



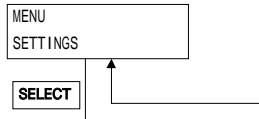
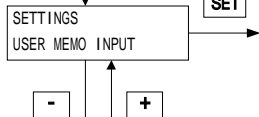
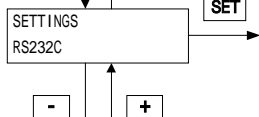
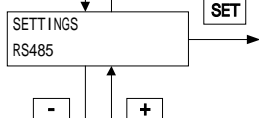
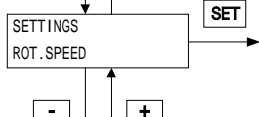
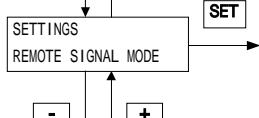
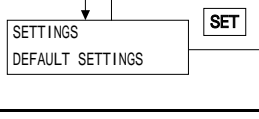
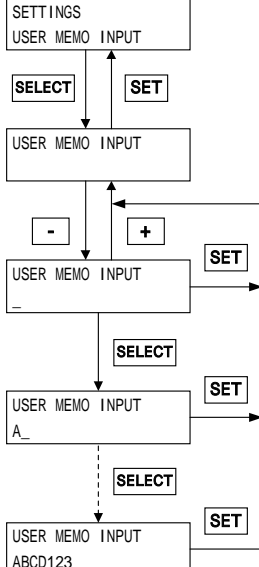
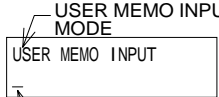
The number of warning that occur for the magnetic bearing system is counted.



Select Reset Counter



(4) MENU MODE/SETTINGS

Mode	Operation and LCD Display	Description of Display
SETTINGS		Select settings mode
USER MEMO SETTINGS		Select user memo settings
RS-232C SETTINGS		Select RS-232C settings
RS-485 SETTINGS		Select RS-485 settings
ROTATIONAL SPEED SETTINGS		Select rotational speed settings
REMOTE-CONTROL SIGNAL SETTINGS		Select remote-control signal settings
DEFAULT SETTINGS		Select default settings
USER MEMO SETTINGS		<p>Setting of any 20 characters is possible. (Ex. Connection name of Turbo Molecular Pump) Characters are displayed during monitor mode.</p>  <p>Press the [+] or [-] key to select characters "A" to "Z", or "0" to "9".</p> <p>A cursor moves to the right when pushes [SELECT] key.</p>

Mode	Operation and LCD Display	Description of Display
RS-232C SETTINGS		<p>Baud rate setting</p> <p>Press the [+] or [-] key to select a baud rate between 19.2k, 9600, 4800, 2400, or 1200.</p> <p>BAUD RATE=9600bps (9600bps)</p> <p>Previous Setting</p> <p>Event Transmission Settings (Note 1)</p> <p>Press the [+] or [-] key to select between ON or OFF.</p> <p>EVENT SENDING=ON (ON)</p> <p>Previous Setting</p> <p>The event sending function is enabled or disabled. If set to ON, an event command is sent from the power supply unit when an event occurs.</p>
RS-485 SETTINGS		<p>Baud rate setting</p> <p>Press the [+] or [-] key to select a baud rate between 19.2k, 9600, 4800, 2400, or 1200.</p> <p>BAUD RATE=9600bps (9600bps)</p> <p>Previous Setting</p> <p>Multi-drop setting (Note 1)</p> <p>Press the [+] or [-] key to select between ON or OFF.</p> <p>MALTDROP=OFF (OFF)</p> <p>Previous Setting</p> <p>Set ON to select the multi-drop mode.</p> <p>Network ID setting (Note 1)</p> <p>Press the [+] or [-] key to select a value between 01 and 32.</p> <p>NETWORK ID=01 (01)</p> <p>Previous Setting</p> <p>Setting required in multi-drop mode.</p> <p>Event Transmission Settings (Note 1)</p> <p>Press the [+] or [-] key to select between ON or OFF.</p> <p>EVENT SENDING=ON (ON)</p> <p>Previous Setting</p> <p>The event sending function is enabled or disabled. If set to ON, an event command is sent from the power supply unit when an event occurs.</p>

(Note 1) See APPENDIX-A "COMMUNICATIONS" for details.

Mode	Operation and LCD Display	Description of Display
REMOTE-CONTROL SIGNAL SETTINGS	<pre> graph TD S1[SETTINGS REMOTE SIGNAL MODE] -- SELECT --> S2[REMOTE SIGNAL MODE ALARM=E1-03] S2 -- SET --> D1[ALARM=E1-03 (E1-03)] S2 -- "+" --> S3[REMOTE SIGNAL MODE REMOTE=E1-03] S3 -- SET --> D2[REMOTE=E1-03 (E1-03)] S3 -- "-" --> S4[REMOTE SIGNAL MODE STOP=REMOTE ONLY] S4 -- SET --> D3[STOP=REMOTE ONLY (REMOTE ONLY)] S4 -- "+" --> S1 S1 -- SET --> S1 </pre>	<p>“ALARM” signal setting of remote-control signal (Note 1)</p> <p>Press the [+] or [-] key to select between E1-03 or SEMI E74.</p> <p>ALARM=E1-03 (E1-03) Previous Setting</p> <hr/> <p>“REMOTE” signal setting of remote-control signal (Note 1)</p> <p>Press the [+] or [-] key to select between E1-03 or SEMI E74.</p> <p>REMOTE=E1-03 (E1-03) Previous Setting</p> <hr/> <p>“STOP” signal setting of remote-control signal (Note 1)</p> <p>Press the [+] or [-] key to select between remote only or remote & RSXXX.</p> <p>STOP=REMOTE ONLY (REMOTE ONLY) Previous Setting</p>
DEFAULT SETTINGS	<pre> graph TD S1[SETTINGS DEFAULT SETTINGS] -- SET --> S2[DEFAULT SETTINGS RESET SETTINGS=NO] S2 -- SELECT --> S1 </pre>	<p>DEFAULT SETTINGS RESET SETTINGS=NO</p> <p>Press the [+] or [-] key to select between NO or YES.</p> <p>Select YES and press the [SET] key to return all the above items to their default settings.</p>

(Note 1) Remote-control signal settings mode

Signals		Description	Pin No.	
ALARM			(20)–(22)	(21)–(22)
	EI-03 *1	alarm occurrence	open	close
		Power OFF and no failure	close	open
	SEMI E74 *2	Power OFF and alarm occurrence	close	open
		No failure	open	close
WARNING			(11)–(13)	(12)–(13)
	EI-03 *1	warning occurrence	open	close
		Power OFF and no failure	close	open
	SEMI E74 *2	Power OFF and warning occurrence	close	open
		No failure	open	close
REMOTE	EI-03 *1	“REMOTE” signal is OFF in power failure regeneration braking even if remote-controlled operation is available.		
	SEMI E74 *2	“REMOTE” signal is always ON when remote-controlled operation is available.		
STOP	REMOTE ONLY	“STOP” signal ((16)-(14) open) is effective for only the time when remote-controlled operation is available.		
	REMOTE & RS-XXX	“STOP” signal ((16)-(14) open) is effective in operation by RS-232C or RS-485 set it in the cases that wants to use hardware inter rock.		

*1 When set to EI-03, behavior of remote-control signals is the same as SHIMADZU Turbo Molecular Pump power supply "EI-03MD" series.

*2 When set to SEMI E74, behavior of remote-control signals conform to SEMI E74 standard "Specification for vacuum Pump Interface-Turbomolecular Pumps"
Refer to the same standard about the shape of connectors and the pin configuration.

(Note 2) default parameters

Function	default settings
User memo	SHIMADZU EI-Dxx03M
RS-232C	BAUD RATE = 9600bps
RS-485	BAUD RATE = 9600bps MULTI DROP = OFF NETWORK ID = 01
Variable speed	DISPLAY = % SPEED = NORMAL LOW SP = 100%
Remote-control signal	ALARM = EI-03 REMOTE = EI-03 STOP = REMOTE ONLY

SECTION 6 OPERATION

(5) MENU MODE/SELF TEST

Mode	Operation and LCD Display	Description of Display
SELF TEST	<pre> graph TD A["MENU SELF TEST"] -- SELECT --> B["SELF TEST SENSOR CHECK"] B -- SET --> A B -- SELECT --> C["SENSOR CHECK CHECK SENSOR=NO"] C -- SET --> B </pre>	<p>Select YES and press the SET key to execute self-diagnosis of the magnetic bearing sensor. If an abnormality is discovered by self-diagnosis, alarm codes 81 to 85 occur. Refer to Table 7-5 for the appropriate remedy. This function can be used only when the pump is stopped.</p> <div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 10px auto;"> SENSOR CHECK CHECK SENSOR=NO </div> <p>Press the + or - key to select between NO or YES.</p>

6.7 Remote-Control Connector

6.7.1 Specifications

The controller is provided with remote-control connector for connection with remote operation, alarm signals, etc. Use this connector and a cable with shield as necessary. The shield of the cable should be connect to case of Remote-connector. (See Figs. 6-9, 6-10, 6-11 and Tables 6-2, 6-3) For remote-controlled operation, shift the REMOTE/LOCAL selection switch (Fig. 2-3 (15)) to REMOTE mode in advance. Fig. 6-9 Remote-Control Connector

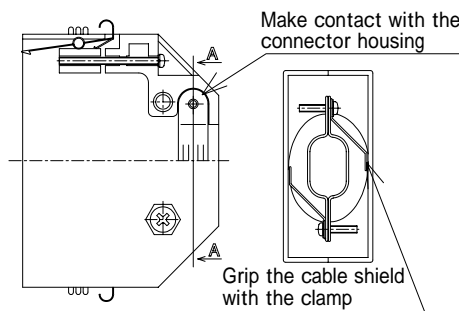
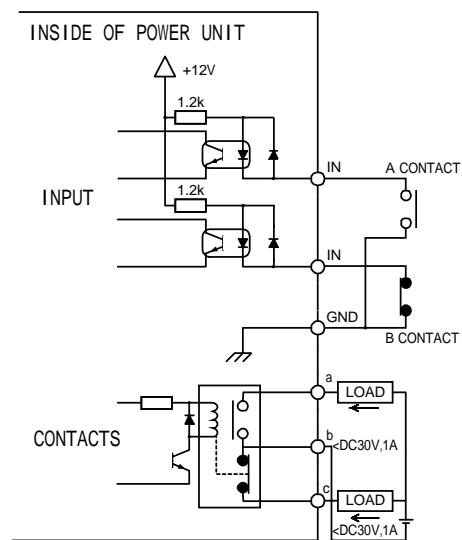


Fig. 6-8 Remote-Control Connector



Remote-Control Circuit

Table 6-2 Start/Stop According to Remote-Control Signals

Connection method	By momentary type START/STOP switch	By alternate type switch
Wiring connection		
Starting	Pump start by short-circuiting (15) and (14). Pump stop by opening (16) and (14).	Pump start, with the contact close or photo transistor ON ((16) to (14) short-circuit) Pump stop, with the contact open or photo transistor OFF ((16) to (14) open)
Electric capacity	[Contact] : It is connected to +12V circuit and subject to stable open-close of DC 5 V, 1mA. Voltage...30VDC or more, Current...10mA or more [Photo transistor] : Select a photo transistor with a collector-emitter voltage limit of 30VDC and an on-state collector current of 10mA or more.	
Input rating	Direct forward current 50mA; DC reverse voltage 5V	

Table 6-3 Remote-Control Signals (Default Settings)

Classification	Signals	Pin No.	Operation	Electric spec.
Inputs	START	(15)	Starting operation on GND and short-circuiting (Note 1)	Contact input
	STOP	(16)	Stopping operation on GND and circuit opening (Note 1) (Note 2)	
	RESET	(17)	Resetting operation on GND an short-circuiting	
	LOW SPEED	(33)	Variable Speed Operation on GND and short-circuiting	
	GND	(14)		
Outputs	ROTATION	(29), (4), (30)	During rotation; (29) - (30) : open _ close (make) (4) - (30) : close _ open (brake)	Contact output Contact capacity (resistance load) 30 VDC 1 A
	NORMAL	(25), (2), (26)	During normal rotation; (25) - (26) : open _ close (make) (2) - (26) : close _ open (brake)	
	ACCELERATION	(23), (1), (24)	During acceleration; (23) - (24) : open _ close (make) (1) - (24) : close _ open (brake)	
	BRAKE	(27), (3), (28)	During deceleration; (27) - (28) : open _ close (make) (3) - (28) : close _ open (brake)	
	REMOTE	(31), (5), (32)	Remote-controlled operation is available; (31) - (32) : open _ close (make) (5) - (32) : close _ open (brake) (Note 2)	
	ALARM (Note 4)	(21), (20), (22)	Against alarm; (21) - (22) : open _ close (make) (20) - (22) : close _ open (brake) (Note 2)	
	WARNING (Note 4)	(12), (11), (13)	Against warning; (12) - (13) : open _ close (make) (11) - (13) : close _ open (brake) (Note 2)	

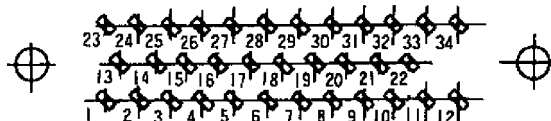
(Note 1) "STOP" signal is prior to "START" signal.

(Note 2) It is possible to change movement by remote-control signal settings of settings mode.

(See Section 6.6 "Software Operation" (4).)

(Note 3) Don't connect any pins other than specified above.

(Note 4) See Table 10-5 "Table of Alarms" and Table 10-6 "Table of Warnings" about alarm and warning.

**Fig. 6-9 Arrangement of Remote-Control Connector Pins**

(The power supply unit rear panel attachment connectors, as viewed from the front)

6.7.2 Compatibility with Previous Models

6.7.2.1 Replacing the EI-xx03M/MD Power Supply Unit

NOTICE

The transistor output has been discontinued. The pins that were used for that output are now assigned to different functions. If wires were connected to these pins with previous models, then simply making the connection as it is could result in a malfunction on the system controller end. Therefore, please revise the wiring.

Replacing EI-xx03M/MD Power Supply Units As-Is (EI-03 Compatible Mode)

(1) Connectors

The shape and pin count of connectors are mutually compatible and can be utilized as-is.

(2) Pin Configuration

It is compatible with EI-xx03M/MD units, except for the transistor output. (See Table 6-4)

(3) Signal Activity

It is compatible with EI-xx03M/MD units.

When using it, changing into SEMI E74 Standard Mode

Change the "ALARM" signal and "REMOTE" signal activation settings from EI-03 to SEMI E74, in accordance with the "Remote-Control Signal Settings" instructions included in the (4) Menu Mode table of Section 6.6 "Software Operation".

(1) Connectors

The shape and pin count of connectors are mutually compatible and can be utilized as-is.

(2) Pin Configuration

The "ALARM" signal pin assignments ("make contact" or "brake contact") are the reverse of EI-xx03M/MD units. If necessary, change the wiring connections.

(3) Signal Activity

The "ALARM" signal and "REMOTE" signal activity differs from EI-xx03M/MD units.

Power Supply Unit	ALARM Signal	REMOTE Signal
EI-xx03M/MD	When the power supply is turned off, the ALARM signal is off.	Remote signal is forcibly off during regenerative braking.
EI-Dxx03M SEMI E74 Settings	When the power supply is turned off, the ALARM signal is on.	Remote signal during regenerative braking depends on the control mode.

Table 6-4 Pin Configuration Comparison Chart (Default Settings)

Signal Type	Signals	Pin numbers		Compatibility
		EI-xx03M/MD	EI-Dxx03M (EI-03Compatible Mode)	
INPUT	START	15	15	Same pin number, same function
	STOP	16	16	
	RESET	17	17	
	LOW SPEED		33	Variable rpm input added
	GND(COMMON)	14	14	Same pin number, same function
OUTPUT1 (Relay Out-put)	ROTATION	29 : Make contact	29 : Make contact	Same pin number, same function
		30 : Common	30 : Common	
			4 : Brake contact	
	NORMAL	25 : Make contact	25 : Make contact	Same pin number, same function
		26 : Common	26 : Common	
			2 : Brake contact	
	ACCELERATION	23 : Make contact	23 : Make contact	Same pin number, same function
		24 : Common	24 : Common	
			1 : Brake contact	
	BRAKE	27 : Make contact	27 : Make contact	Same pin number, same function
		28 : Common	28 : Common	
			3 : Brake contact	
	ALARM	21 : Make contact	21 : Make contact	Same pin number, same function
		22 : Common	22 : Common	
		20 : Brake contact	20 : Brake contact	
WARNING		11 : Brake contact	Added function	
		13 : Common		
		12 : Make contact		
REMOTE	31 : Make contact	31 : Make contact	Same pin number, same function	
	32 : Common	32 : Common		
		5 : Brake contact		"Brake contact" added
OUTPUT2 (Transistor Output)	MOTOR	3		Removed function
	MAG.BEARING	4		EI-Dxx03M units have a pin assigned to the "Brake contact" output terminal of OUTPUT1
	POWER FAILURE	5		
	PUMP TEMP.	7		(If wiring is connected to the pin for EI-xx03M/MD units and is used without modification, a malfunction could occur on the system controller side, so please remove it.)
	CONT. TEMP.	8		
	V(+)	1		
	COM(-)	2		

6.7.2.2 Replacing EI-xx03MZ Power Supply Units

If using the remote control signal for previous EI-xx03MZ power supply units (where "xx" is a number that indicates the applicable pump type), then the following checks and changes to settings are necessary when replacing the unit with an EI-Dxx03M model.

Change the "ALARM" signal and "REMOTE" signal activation settings from EI-03 to SEMI E74, in accordance with the "Remote-Control Signal Settings" instructions included in the (4) Menu Mode table of Section 6.6 "Software Operation".

(1) Connectors

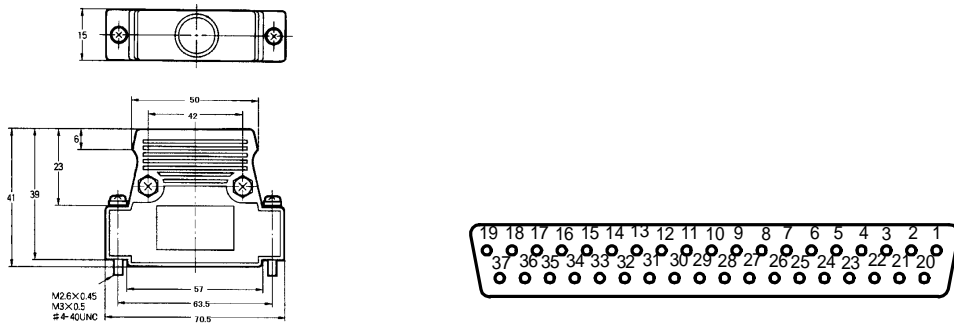
The shape and pin count are both different. (See Figure 6-12)

(2) Pin Configuration

Different. (See Table 6-5)

(3) Signal Activity

Once the settings have been changed, it is compatible with SEMI 74 Standard Mode.



Remote-Control Connector

Arrangement of Remote-Control Connector Pins
(The power supply unit rear panel attachment connectors, as viewed from the front)

Fig. 6-10 Previous EI-xx03MZ Model Remote Control Connector and Pin Configuration

**Table 6-5 EI-xx03MZ vs. EI-Dxx03M Pin Configuration Comparison Chart
-After Changing Settings (SEMI E74 Standard Mode)**

Signal type	Signals	Pin numbers		Compatibility
		EI-xx03MZ	EI-Dxx03M SEMI E74 Standard Mode	
INPUT	START	2	15	Same function
	STOP	3	16	
	RESET	4	17	
	LOW SPEED	6	33	
	GND(COMMON)	1	14	
OUTPUT (Relay Output)	ROTATION	17 : Make contact	29 : Make contact	
		19 : Common	30 : Common	
		18 : Brake contact	4 : Brake contact	
	NORMAL	11 : Make contact	25 : Make contact	
		13 : Common	26 : Common	
		12 : Brake contact	2 : Brake contact	
	ACCELERATION	8 : Make contact	23 : Make contact	
		10 : Common	24 : Common	
		9 : Brake contact	1 : Brake contact	
	BRAKE	14 : Make contact	27 : Make contact	
		16 : Common	28 : Common	
		15 : Brake contact	3 : Brake contact	
	ALARM	27 : Make contact	20 : Make contact	
		28 : Common	22 : Common	
		26 : Brake contact	21 : Brake contact	
	WARNING	30 : Make contact	11 : Make contact	
		31 : Common	13 : Common	
		29 : Brake contact	12 : Brake contact	
	REMOTE	20 : Make contact	31 : Make contact	
		22 : Common	32 : Common	
		21 : Brake contact	5 : Brake contact	

TROUBLESHOOTING



- 7.1 Nothing Happens After an Operation is Made
- 7.2 Power Failures
- 7.3 Vacuum Pressure Rise
- 7.4 Abnormal Noise and/or Vibration
- 7.5 Alarm Detection Capabilities

7.1 Nothing Happens After an Operation is Made

Table 7-1 Nothing Happens After an Operation is Made

	PROBLEM	POSSIBLE CAUSES	CORRECTIVE ACTION
1	Power ON/OFF switch in the ON position but the turbo molecular pump fails to operate.	Electrical power cable not properly connected.	Properly connect the electrical power cable.
		Electrical power outside power supply unit's power range.	Operate within power supply unit's power range.
		Blown fuse (F1, F2)	Replace blown fuse.
		POWER switch fails to the off position.	Replace POWER switch. Consult the nearest Shimadzu service company.
2	START switch pressed but turbo molecular pump does not accelerate.	REMOTE/LOCAL selection switch in the REMOTE position.	Set the REMOTE/LOCAL selection switch in the LOCAL position.
		Other causes.	Check the power supply unit's ALARM lamp is not ON. If an alarm is indicated, correct the malfunction and reset the power supply unit.
3	Remote "START" signal active but the turbo molecular pump does not accelerate.	REMOTE/LOCAL selection switch in LOCAL position.	Set the selection switch in the REMOTE position.
		"STOP" signal active.	Deactivate "STOP" signal.
		Other problems.	Check the unit's ALARM lamp is not ON. If an alarm is indicated, correct the malfunction and reset the power supply unit.
4	STOP switch pressed but the turbo molecular pump does not decelerate.	REMOTE/LOCAL selection switch is in the REMOTE position.	Set the selection switch in the LOCAL position.
5	Remote "STOP" signal activated but the turbo molecular pump does not decelerate.	REMOTE/LOCAL selection switch is in the LOCAL position.	Set the selection switch in the REMOTE position.

7.2 Power Failures

When a power interruption occurs, the motor inside the turbo molecular pump immediately begins regenerative braking. The magnetic bearing will use this generated electricity to keep functioning and the rotor inside the turbo molecular pump will continue being levitated. The rotation will slow down due to the regenerative braking and eventually the rotor will be supported by the touchdown bearing. Table 7-2 shows the number of revolutions and period of time that will elapse before being supported by the touchdown bearing, when the power fails at the rated speed.

Table 7-2 Time and Rotational Speed During a Power Interruption Before Being Supported by Touchdown Bearing

Pump Model	Power Supply Model	Rotational Speed Before Support by Touchdown Bearing	Period of Time Before Support by Touchdown Bearing (Note 1)
TMP-803M/MC/LM/LMC TMP-1003M/MC/LM/LMC	EI-D1003M	7200rpm	about 4 minutes
TMP-1103MP/MPC/LMP/LMPC	EI-D1103M	7200rpm	about 4.5 minutes
TMP-1303M/MC/LM/LMC	EI-D1303M	7800rpm	about 5.5 minutes
TMP-2003M/MC/LM/LMC	EI-D2003M	5400rpm	about 10 minutes
TMP-2203M/MC/LM/LMC	EI-D2203M	5400rpm	about 14 minutes
TMP-3203M/MC/LM/LMC	EI-D3203M	5400rpm	about 15.5 minutes
TMP-3403LMC	EI-D3403M	5400rpm	about 17 minutes
TMP-4203LMC	EI-D4203M	4200rpm	about 22 minutes

Note 1) Times are typical for regenerative braking from the rated speed.

Actual times will vary depending on vacuum conditions inside the pump and the rotational speed when the power fails.

7.2.1 Power Failure Counter-Operation

Table 7-3 shows the counter-operations against power supply failure which occurred while the pump rotor is normally rotating.

Table 7-3 Counter-Operations Against Power Supply Failure

Interruption time	1 second or less		Over 1 second	
	During interruption	After re-supply	During interruption	After re-supply
Magnetic levitation	Levitation goes on	Levitation goes on	Levitation goes on	Levitation goes on
Run	Decelerates	Returns to before-power-failure running condition	Decelerates	Decelerates (Note 1)
Indicator lamp ROTATION NORMAL SPEED ALARM (Note 2) Remote-control output signals ROTATION Pin no. (29)-(30) (4)-(30) NORMAL Pin no. (2)-(26) (25)-(26) ACCELERATION Pin no. (1)-(24) (23)-(24) BRAKE Pin no. (27)-(28) (3)-(28) REMOTE Pin no. (31)-(32) (5)-(32) ALARM Pin no. (21)-(22) (20)-(22)	Before-power-failure indication goes on. Before-power-failure indication goes on. Before-power-failure indication goes on.	Before-power-failure condition goes on. Before-power-failure condition goes on. Before-power-failure condition goes on.	Lamp ON goes on Turns OFF Turns ON Contact close Contact open Contact close Contact open Contact close Contact open Contact close Contact open Contact open Contact close Contact close Contact open	Lamp ON goes on. Lamp OFF goes on. Lamp ON goes on. "CLOSE" goes on "OPEN" goes on "CLOSE" goes on "OPEN" goes on "CLOSE" goes on "OPEN" goes on "CLOSE" goes on "OPEN" goes on Return to Before-power-failure condition By resetting, "CLOSE" _ "OPEN" "OPEN" _ "CLOSE"
WARNING Pin no. (12)-(13) (11)-(13)	"OPEN" goes on "CLOSE" goes on		Contact open Contact close	By resetting, Contact open Contact close
Buzzer	Does not sound	Does not sound	(Note 1) Before resetting: Sounds After resetting: Released (reset)	(Note 1) Before resetting: Sounds After resetting: Released (reset)

(Note 1) For restarting after the power re-supply (restoration), press the RESET switch twice and, thereafter, perform the start-up operation. First pressing of the RESET releases the buzzer and second pressing of the RESET releases "ALARM" signal.

(Note 2) The pin numbers are shown in Fig. 6-11 Arrangement of Remote-Control Connector Pins.

(Note 3) The ALARM, WARNING and REMOTE signal activity will change depending on the SETTINGS/REMOTE SIGNAL MODE menu settings on the LCD display. For more information, refer to Section 6.6 "Software Operation".

7.3 Vacuum Pressure Rise

A rapid rise of vacuum pressure in the turbo molecular pump causes the internal motor of the turbo molecular pump to start braking and the ALARM lamp (Fig. 2-3 (14)) lights.

7.4 Abnormal Noise and/or Vibration

Should the turbo molecular pump ever generate abnormal noise and/or vibration, the turbo molecular pump operation is to be stopped immediately.

But there is possible that a race of touch-down bearing (Fig. 3-1 (9)) may make sounds for seconds when the pump internal pressure gets back to atmospheric pressure using air (or non-activity gas). This phenomena is not abnormal and make no damage to the pump, because the air whirlpool sometimes occurs and then makes the touch-down bearing rotate slightly.

CAUTION

When turning the POWER switch for the power supply unit on or off, a "clunk" sound may be heard from inside the pump. This sound is from the rotor inside the pump being levitated or de-levitated. This is normal.

7.5 Alarm Detection Capabilities

The fault detection functions shown in Table 7-6 "Table of Alarms" and Table 7-7 "Table of Warnings" are incorporated for protection in the event of a problem with the turbo molecular pump or power supply unit.

When an error is detected, check the ALARM lamp (Fig. 2-3 (14)) and the alarm mode display on the front panel (See Section 6.6 "Software Operation" (2)) and refer to Tables 7-4 and 7-5 for the appropriate remedy.

7.5.1 Movement in Alarm Detection Capabilities (ALARM)

1. ALARM lamp (Fig. 2-3 (14)) lights.
2. The remote-control connector "ALARM" signal turn ON.
3. The buzzer sounds.
4. The pump start the protective operations shown in Table 7-6 "Table of Alarms."

7.5.2 Movement in Alarm Detection Capabilities (WARNING)

1. ALARM lamp (Fig. 2-3 (14)) flashes.
2. The remote-control connector "WARNING" signal turn ON.
3. The buzzer sounds.
4. Pump operation continues.

7.5.3 Reset Procedure

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1. When the reset procedure is conducted once, the buzzer stops.
2. Refer to the Troubleshooting information and eliminate the cause of the problem.
3. Conduct the reset operation again.
4. (ALARM) If the problem has been eliminated, the ALARM lamp (Fig. 2-3 (14)) goes out, the "ALARM" remote-control signals (see Table 6-3) turn OFF after an alarm was given, the pump rotor decelerates rotational speed.
(WARNING) When the problem is eliminated after a warning occurred, pump operation continues.
5. If the problem was not completely eliminated, the buzzer sounds again and the error is detected.

Table 7-4 If the ALARM Lamp Lights

	LCD Display	Possible Cause	Remedy	Section
1	11=TD COUNTER LIMIT 12=PF COUNTER LIMIT	The number of high speed or power failure touch-downs has exceeded the prescribed number.	The touch-down bearing may have deteriorated. Consult Shimadzu or an approved service company regarding replacement of the touch-down bearing.	
2	13=WRONG TMP MODEL	The models of pump and power supply do not match.	Check the combination of the pump and power supply models. Check the connection of the magnetic bearing cable. Also check that the connector pins are not bent. Turn off the power supply before checking the magnetic bearing cable. Never disconnect the cable while the power is on.	5.3
3	14=AC LOW VOLTAGE 15=POWER FAILURE	Power failure or reduction in the power supply voltage.	Wait for the power to be restored. An unfamiliar sound will be heard a few minutes after a power failure. This sound occurs when the rotor contacts the protective bearing as magnetic levitation cannot be maintained. This is not an abnormal sound.	
		POWER switch was turned off by mistake.	Wait about 5 seconds before turning the POWER switch back on. Re-acceleration is possible after resetting and start-up.	
4	16=TMP:OVERLOAD	Drop in rotation speed during rotation at rated speed (increased internal pump pressure).	Check that the outlet and inlet pressures are below the specified maximum pressures. Check for leakage. Check that too much purge gas is not flowing. Check that process gas flow rate is not too high.	

SECTION 7 TROUBLESHOOTING

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	LCD Display	Possible Cause	Remedy	Section
5	21=TMP TEMP/MB CABLE	High pump unit temperature.	Check that the ambient temperature around the pump is within the specified range. For the air-cooled models, check that the cooling fan is operating and cooling is not hindered by peripheral objects. For water-cooled models, check that the temperature and flow rate of the cooling water are within the specified ranges. Check that no load in excess of the specified range is continuously applied to the pump.	
		Magnetic bearing cable is not connected correctly.	Check the connection of the magnetic bearing cable. Also check that the connector pins are not bent. Turn off the power supply before checking the magnetic bearing cable. Never disconnect the cable while the power is on.	5.3
6	22=TMP:SENSOR ERROR 46=MOTOR OVERSPEED 47=EI:R-SPEED ERROR	Rotation detection signal from the motor cannot be detected correctly.	Check that equipment causing noise is not used around the power supply unit, pump unit, motor cable, or magnetic bearing cable.	5.1 5.2 5.3
7	23=EI:MOTOR OVERCURR 34=EI:INV. OVERCURR	Overcurrent supplied to the motor.	Check the motor cable and magnetic bearing cable. (Check for connection and wiring likely to cause disconnection or short circuit.)	
8	31=EI:BR OVERTEMP 32=EI:DC-DC OVERTEMP	Temperature increase in the power supply unit.	Check that the ambient temperature around the power supply unit is within the specified range.	4.1
			Check the ventilation of the power supply unit.	5.1
9	33=EI:FAN ERROR	Fan stopped.	Check that the fan on the power supply unit rear panel is operating. Remove any object obstructing its operation.	5.1
10	35=EI:INV. OVERVOLT 36=EI:DC-DC LOW VOLT 37=EI:DC-DC OVERCURR 38=EI:DC-DC OVERVOLT 45=EI:BRAKE OVERTIME	Defective circuit in the power supply unit.	Turn the power on again after the pump stops. The power supply unit must be repaired if the problem occurs again.	
			Turn the power on again after the pump stops. The power supply unit must be repaired if the problem occurs again.	
11	43=EI:PARAM ERROR	Defective circuit in the power supply unit.	Turn the power on again after the pump stops. The power supply unit must be repaired if the problem occurs again.	

	LCD Display	Possible Cause	Remedy	Section
12	44=EI:CPU ERROR 66=MB:DSP ERROR 67=MB:DPS OVERFLOW	Abnormal operation of circuit in the power supply unit.	Check that the ambient temperature around the power supply unit is within the specified range. Check that equipment causing noise is not used around the power supply unit, pump unit, motor cable, or magnetic bearing cable.	4.1 5.1 5.2 5.3
13	48=EI:ACCEL OVERTIME	Rotation speed does not increase at start-up.	Check that the outlet and inlet pressures are not too high. Check for leakage. Check that too much purge gas is not flowing.	6.2
14	49=TMP:CAN NOT START	Pump does not rotate.	Adhesion of reaction products or damage to the protective bearing is the possible cause. Remove the pump from the unit and check that the rotor blades rotate smoothly at the inlet. An overhaul is required if blades do not rotate smoothly.	
15	51=MB:VIBRATION2 X1 52=MB:VIBRATION2 Y1 53=MB:VIBRATION2 X2 54=MB:VIBRATION2 Y2 55=MB:VIBRATION2 Z 56=MB:VIBRATION X1 57=MB:VIBRATION Y1 58=MB:VIBRATION X2 59=MB:VIBRATION Y2 60=MB:VIBRATION Z	Strong external shock or vibrations.	If the shock or vibrations are transient, re-acceleration is possible. If the shock or vibrations occur frequently, stop the pump and remove the source of the shock or vibrations; or re-examine the pump mounting method.	
16	61=MB:SENSOR ERR. X1 62=MB:SENSOR ERR. Y1 63=MB:SENSOR ERR. X2 64=MB:SENSOR ERR. Y2 65=MB:SENSOR ERR. Z	Magnetic bearing cable is not connected correctly.	Check the connection of the magnetic bearing cable. Also check that the connector pins are not bent. Turn off the power supply before checking the magnetic bearing cable. Never disconnect the cable while the power is on.	5.3
17	68=MB:BALANCE AXIS1 69=MB:BALANCE AXIS2	Rotor inside the pump is out of balance.	Adhesion of reaction products is a possibility. An overhaul is required.	

Table 7-5 If the ALARM Lamp Flashes

	LCD Display	Possible Cause	Remedy	Section
1	81=MB:SELF CHECK X1 82=MB:SELF CHECK Y1 83=MB:SELF CHECK X2 84=MB:SELF CHECK Y2 85=MB:SELF CHECK Z	Rattling of the protective bearing becomes pronounced.	Deterioration of the protective bearing is likely. Overhaul as soon as possible to avoid damage to the protective bearing in the event of a power failure etc.	
2	86=MB:VIB. WARN. X1 87=MB:VIB. WARN. Y1 88=MB:VIB. WARN. X2 89=MB:VIB. WARN. Y2 90=MB:VIB. WARN. Z	Transient strong external shock or vibrations.	Continuous operation is possible. However, if the shock or vibrations occur frequently, stop the pump and remove the source of the shock or vibrations; or re-examine the pump mounting method.	
3	91=MB:BALANCE WARN.1 92=MB:BALANCE WARN.2	Rotor inside the pump is out of balance.	Adhesion of reaction products is a possibility. An overhaul is recommended.	
4	93=MB:AIR RASH A 94=MB:AIR RASH B	Atmospheric penetration has occurred.	Create a vacuum system not allowing atmospheric penetration by re-examining the operating sequence of the back pump and valves etc.	
5	99=MAINTENANCE TIME	Maintenance call timer has reached the set time.	Implement maintenance works prescribed by the customer, such an overhaul. The alarm can be cancelled by resetting the maintenance call timer after implementing necessary works.	6.6

Table 7-6 Table of Alarms

Alarm Code	LCD Display	Cause	Protective Action
11	11=TD COUNTER LIMIT	Counts of the high speed touch-down counter exceeded the specified number.	Start-up impossible (detected during power supply self-diagnostics)
12	12=PF COUNTER LIMIT	Counts of the power failure touch-down counter exceeded the specified number.	
13	13=WRONG TMP MODEL	The combination of the pump and power supply is wrong.	
14	14=AC LOW VOLTAGE	Fall in AC input power voltage.	Regenerative braking
15	15=POWER FAILURE	Power failure.	
16	16=TMP:OVERLOAD	After accelerating to 80% of the designated speed or low-speed setting, the speed dropped below 80% due to overloading etc.	Deceleration
21	21=TMP TEMP/MB CABLE	Increased pump drive motor temperature. MB cable is not connected.	Free run (motor stop)
22	22=TMP:SENSOR ERROR	Pump rotation signal could not be detected correctly.	
23	23=EI:MOTOR OVERCURRE	Overcurrent ran through the motor.	
24	24=TMP PUMP TEMP	Pump Temperature	
31	31=EI:BR OVERTEMP	Increased temperature inside power supply unit.	
32	32=EI:DC-DC OVERTEMP	Increased temperature inside power supply unit.	
33	33=EI:FAN ERROR	Power supply cooling fan has stopped.	
34	34=EI:INV. OVERCURRE	Overcurrent ran through the motor.	
35	35=EI:INV. OVERVOLT	Defective circuit in the power supply.	
36	36=EI:DC-DC LOW VOLT	Defective circuit in the power supply.	
37	37=EI:DC-DC OVERCURRE	Defective circuit in the power supply.	Deceleration
38	38=EI:DC-DC OVERVOLT	Defective circuit in the power supply.	
43	43=EI:PARAM ERROR	Stored parameters are not correct.	Start-up impossible (detected during power supply self-diagnostics)
44	44=EI:CPU ERROR	Error in the CPU for inverter control.	Free run (motor stop)
45	45=EI:BRAKE OVERTIME	Pump does not stop within the specified time after the stop operation.	
46	46=MOTOR OVERSPEED	Pump rotation speed is too high.	
47	47=EI:R-SPEED ERROR	Pump rotation speed cannot be detected.	

SECTION 7 TROUBLESHOOTING

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Alarm Code	LCD Display	Cause	Protective Action
48	48=EI:ACCEL OVERTIME	Pump does not accelerate to 80% of the designated speed or low-speed setting within the specified time after start-up.	Deceleration
49	49=TMP:CAN NOT START	Pump fails to rotate within 15 seconds after start-up.	
51	51=MB:VIBRATION2 X1	Continuous excessive vibration of the magnetic bearing.	
52	52=MB:VIBRATION2 Y1		
53	53=MB:VIBRATION2 X2		
54	54=MB:VIBRATION2 Y2		
55	55=MB:VIBRATION2 Z		
56	56=MB:VIBRATION X1	Excessive magnetic bearing vibration.	
57	57=MB:VIBRATION Y1		
58	58=MB:VIBRATION X2		
59	59=MB:VIBRATION Y2		
60	60=MB:VIBRATION Z		
61	61=MB:SENSOR ERR. X1	Abnormal output signal from the magnetic bearing sensor.	
62	62=MB:SENSOR ERR. Y1		
63	63=MB:SENSOR ERR. X2		
64	64=MB:SENSOR ERR. Y2		
65	65=MB:SENSOR ERR. Z		
66	66=MB:DSP ERROR	Error in the DSP for magnetic bearing control.	
67	67=MB:DPS OVERFLOW	Overflow in the magnetic bearing control calculations.	
68	68=MB:BALANCE AXIS1	Rotor is out of balance.	
69	69=MB:BALANCE AXIS2		

Table 7-7 Table of Warnings

Alarm Code	LCD Display	Causes	Protective Action
81	81=MB:SELFCHECK X1	Results of magnetic bearing sensor self-diagnostics are abnormal.	Operation is possible (detected during power supply self-diagnostics).
82	82=MB:SELFCHECK Y1		
83	83=MB:SELFCHECK X2		
84	84=MB:SELFCHECK Y2		
85	85=MB:SELFCHECK Z		
86	86=MB:VIB. WARN. X1	Vibrations of the magnetic bearing become temporarily excessive.	Operation continued.
87	87=MB:VIB. WARN. Y1		
88	88=MB:VIB. WARN. X2		
89	89=MB:VIB. WARN. Y2		
90	90=MB:VIB. WARN. Z		
91	91=MB:BAL. WARN. AXIS1	Rotor is slightly out of balance.	
92	92=MB:BAL. WARN. AXIS2		
94	94=MB:AIR RASH B	Atmospheric penetration.	
99	99=MAINTENANCE TIME	Maintenance call timer reaches its set time.	

Appendix A

COMMUNICATIONS



- A1. GENERAL SPECIFICATION
- A2. INTERFACE SPECIFICATION
 - A2.1 RS-232C
 - A2.2 RS-485
- A3. POWER SUPPLY TO COMPUTER CONNECTION
 - A3.1 Communication Cable Connection
 - A3.2 Serial Communications Baud Rate Configuration
 - A3.3 RS-485 Multi-drop Settings
- A4. SERIAL COMMUNICATIONS PROTOCOL
- A5. TABLE OF COMMANDS
- A6. COMMAND DESCRIPTION
 - A6.1 Operation Mode
 - A6.2 Operation
 - A6.3 Run Status
 - A6.4 Parameters
 - A6.5 Events
 - A6.6 Timer
 - A6.7 History
 - A6.8 Settings
 - A6.9 Shared Answer
- A7. RS-232C COMMANDS / ANSWERS
- A8. RELATION OF LOCAL MODE TO REMOTE MODE OPERATIONS
- A9. TROUBLESHOOTING
 - A9.1 No Message can Transmit and Receive
 - A9.2 Sending and Receiving are Done, But Receivable Messages are Invalid
 - A9.3 Characters Get Disordered from Time to Time, Then Resulting in CHECKSUM Error

A A1. GENERAL SPECIFICATION

The EI-D03M series power supply units contain serial interfaces conforming to RS-232C and RS-485 specifications. The following functions are available by connecting a computer with communication capacity to these interfaces and creating the appropriate software.

The RS-232C and RS-485 interfaces can be used simultaneously, permitting simultaneous access from two computers. Also, the RS-485 interface permits multi-drop connections, allowing multiple power supplies to be connected to a single computer.

1. Checking current operation mode: The serial interfaces allow the user to check the mode selection switch status (REMOTE/LOCAL). In REMOTE mode, the user can change the operation mode to RS-232C or RS-485.
2. Operation: Operations equivalent to the START, STOP, and RESET switches are available in the RS-232C or RS-485 operation mode. Also, the speed setting can be made using the set value write function.
3. Checking turbo molecular pump run status: The serial interfaces allow the user to check the current turbo molecular pump's running status (Normal rotation, Accelerating, Decelerating, failure occurrence, etc.).
4. Reading parameters: The serial interfaces allow the user to read a variety of turbo molecular pump parameters such as pump rotational speed and motor current which are stored in the power supply unit.
5. Receiving events: The power supply unit can transmit status commands for events such as failure occurrences, rotation start and stop, and attainment of normal rotation speed.
6. Reading history data: The serial interfaces allow the user to read the alarm history data displayed in the LCD display history mode.
7. Reading and writing timer data: The serial interfaces allow the user to read the timer and counter values displayed in the LCD display timer mode and to reset the counters.
8. Reading and writing settings data: The serial interfaces allow the user to read and change settings in the LCD display setting mode.

A2. INTERFACE SPECIFICATION

A2.1 RS-232C

A2.1.1 Transmission Specification

Interface	RS-232C
Synchronous system	Asynchronous
Transmission rate	1200, 2400, 4800, 9600 and 19.2k bits per second (See Section 6.6 "Software Operation" (4) for settings).
Character configuration	Start bit: 1 Data bits: 8 Parity: None Stop bits: 1
Flow control	None

A2.1.2 Communications Connector

Connector	Rear panel RS-232C connector (See Section 2.1 "Power Supply Unit").
Connector type	D-Sub 9-pin, Male
Pin assignment	2 : RD (Receive data) 3 : SD (Transmit data) 4 : ER (Data terminal ready) 5 : SG (Signal ground) 7 : RS (Transmit request) * Other pins are not connected. ER and RS are on during the power supply unit's power up.

A2.1.3 CABLE

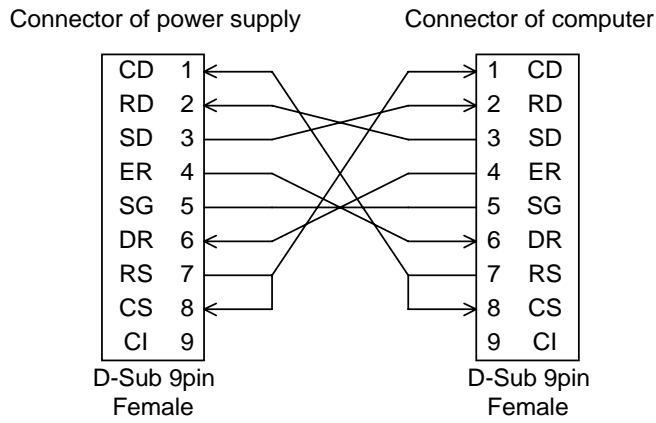
(1) Cable Connection

Use the connection cable as shown in Figs. A-1 to connect the power supply and computer.
(Number on figure is pin number of connector.)

(2) Cable Length

Connection cables can be extended up to 15 meters, but may be subjects to errors depending on actual operational environment.

a. Cable wiring connections for 9-pin to 9-pin connector cables



b. Cable wiring connections for 9-pin to 25-pin connector cables

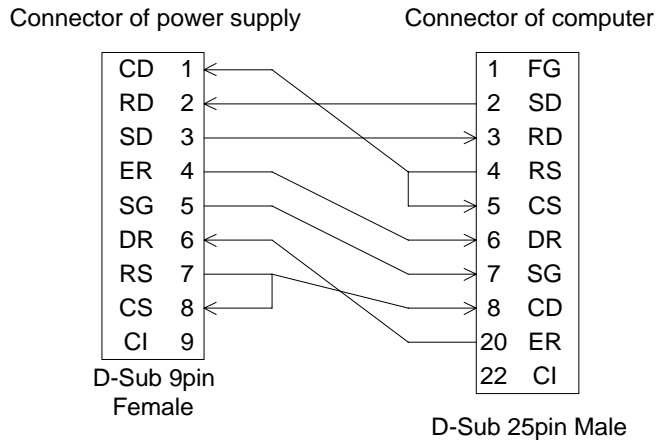


Fig. A-1 Example of RS-232 cable wiring connections

A2.2 RS-485

A2.2.1 Transmission Specification

Interface	RS-485
Synchronous system	Asynchronous
Transmission rate	1200, 2400, 4800, 9600 and 19.2k bits per second (See Section 6.6 “Software Operation” (4) for settings).
Character configuration	Start bit: 1 Data bits: 8 Parity: None Stop bits: 1
Flow control	None
Number of power supply	Multi-drop function OFF: 1 Multi-drop function ON: Max 32 (*1)

*1 : There may be restrictions depending on cable length or cable type. Perform appropriate checks in the actual operating environment.

A2.2.2 Communications Connector

Connector	Rear panel RS-485 connector (See Section 2.1 “Power Supply Unit”).
Connector type	D-Sub 9-pin, Female
Pin assignment	1, 6 : RxA (Receive data +) 2, 7 : RxB (Receive data -) 3, 8 : TxB (Transmit data -) 4, 9 : TxA (Transmit data +) * Other pins are not connected.

A2.2.3 CABLE

- (1) Cable Connection
 - a. Multi-drop function OFF

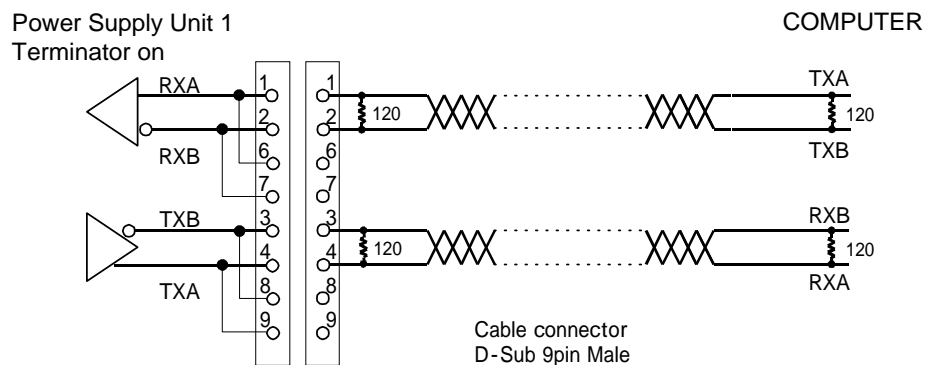


Fig. A-2 Example of RS-485 cable wiring connections (Multi-drop function OFF)

b. Multi-drop function ON

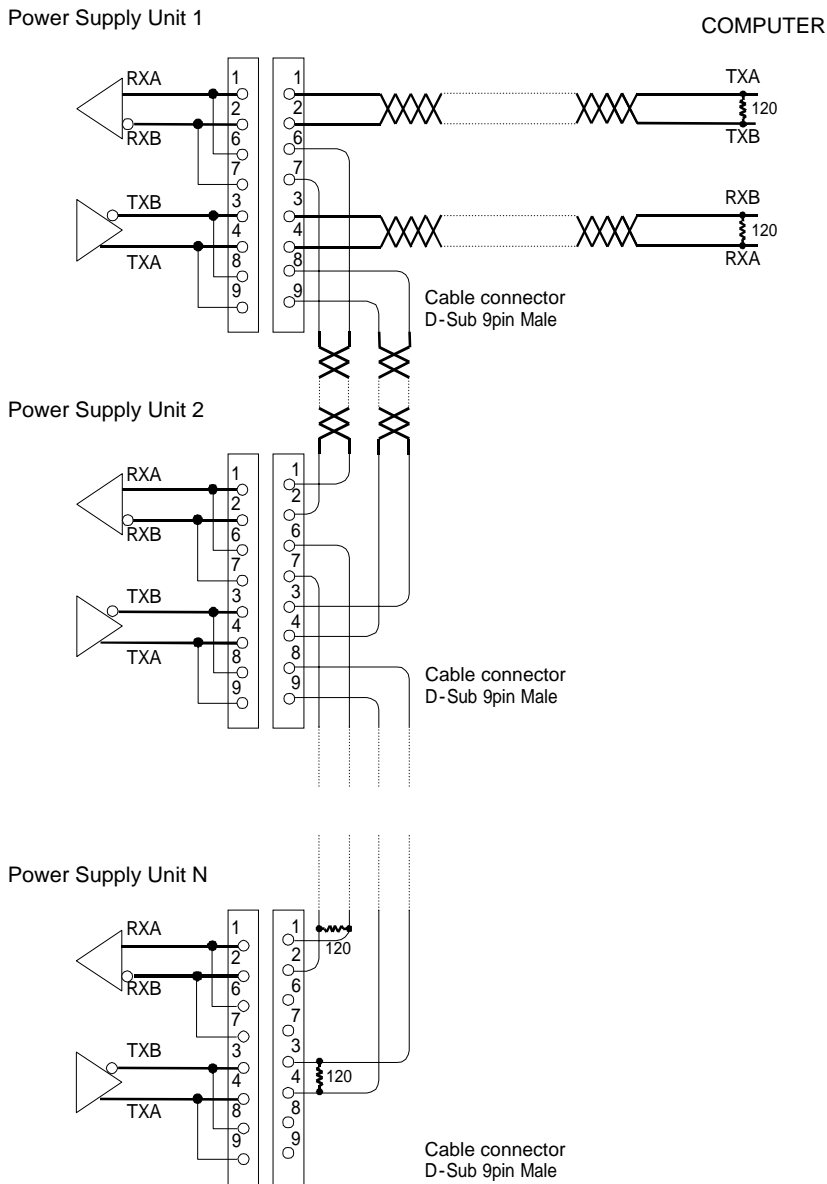


Fig. A-3 Example of RS-485 cable wiring connections (Multi-drop function ON)

(2) Cables used

RS-485 is a differential transmission and use twisted-pair cables in combinations as shown in Figs. A-2 and A-3.

(3) Connecting the terminator

Prepare terminators (120 ohm resistor) when connecting the computer to the power supply unit.

Terminators are not required for any power supply unit in a multi-drop connection with an EI-D03M series power supply unit or computer on each side (corresponding to EI-D03M series units 1 to (N-1) in Fig. A-3).

(4) Cable Length

Connection cables can be extended up to 1.2 kilometers, but may be subjects to errors depending on actual operational environment.

A3. POWER SUPPLY TO COMPUTER CONNECTION

A3.1 Communication Cable Connection

Turn off the power supply unit and the computer to be connected. Connect the RS-232C connector on the power supply unit front panel or the RS-485 connector on the rear panel (refer to section 2.2 in this document, "Power Supply Unit") to the communications port of the computer with a cable, referring to section A2.

A3.2 Serial Communications Baud Rate Configuration

Check with a baud rate of a computer connected to, and set up a baud rate of RS-232C or RS-485. See Section 6.6 "Software Operation" (4) for details about the setting method.

A3.3 RS-485 Multi-drop Settings

The RS-485 interface multi-drop function is used to connect multiple power supply units to a single computer. Turn off the multi-drop function if the RS-485 is used instead of RS-232C to extend the communication cable length.

When the multi-drop function is turned on, the network ID portion of the sent character strings (see Section A4) is enabled and the event communication function that notifies the power supply unit status to the connected computer is disabled.

Set up the RS-485 as described below when using a multi-drop connection.

(1) Turn On the Multi-drop Function

Turn ON the multi-drop function using setting mode/RS485 setting/multi-drop setting on the LCD display. See Section 6.6 "Software Operation" (4) for details about the setting method.

(2) Setting the Network ID

The network ID is set using setting mode/RS485 setting/network ID setting on the LCD display to designate which power supply connected via the multi-drop connection the computer is sending commands to.

The network ID is set as a number between 01 and 32, and must be unique for each power supply connected to a computer. See Section 6.6 "Software Operation" (4) for details about the setting method.

When the RS-485 interface multi-drop function is turned ON, the event sending function (See A6.5) will be disabled, regardless of the SETTINGS/RS485/EVENT SENDING menu settings on the LCD display.

A4. SERIAL COMMUNICATIONS PROTOCOL

Communications software, between the power supply and customer equipment should be design according to the following specifications.

A4.1 Basic Message Structure

A basic transmit and receive message begins with the characters "MJ" and ends with a carriage return code (0dH : xxH means hexadecimal code). (See Table A-1)
The first message to be sent is referred as the COMMAND, while the reply to the command is referred as the ANSWER.

Table A-1 Basic structure of Commands and Answers

Character	Hex. Code	Description	Number Of Bytes
M	4d	Command header characters	2
J	4a		
0	30	Network ID	2
1	31	Multi-drop function OFF: 01 fixed Multi-drop function ON: 01 to 32	
X	xx	Command Characters	2
X	xx		
		Sub-command Characters	X
f	xx	Checksum characters (Calculation result by Section A4.7 enters it.)	2
f	xx		
CR	0d	Carriage return character	1

A4.2 Character to Character Time-out: 0.1 sec.

Delays between characters, in the answer message, longer that 0.1 sec., shall be considered as a transmission line failure and special considerations should be made to re-send the message.

A4.3 Command to Answer Time-out: 1 sec.

Delays between COMMAND and ANSWER messages, longer than 1 sec., shall be considered as a transmission line failure and special considerations should be made to re-send the message.

The power supply re-sends a COMMAND, if it does not receive an ANSWER within a one second period.

A4.4 Power Supply Command Send Retry Cycles: 5

If the power supply does not receive an answer to a command, within one second, it will re-send the same command up to a maximum of five times.

A4.5 Command Transmission Specification

A command sent before an answer is sent, will be ignored by the power supply, until a reply to the first command is sent. However, this does not apply after a transmission time-out occurs between command and answer. (If processing is performed normally, an answer is returned within 100 msec.)

A4.6 Receiving Sequence

The character string from the power supply unit is received after the COMMAND character string is sent. When the carriage return code (0dH) is received, the received character string is checked from the beginning and the portion from the initial command header "MJ" to the carriage return code received last is processed as an answer.

Initialize the receive buffer after the answer character string is acquired from the receive buffer. The read user memo (described below) may receive the same "MJ" as the command header character string in the answer character string. Therefore, interpret the character string from the first "MJ" appearing in the receive buffer to the carriage return as the answer character string.

A4.7 Using the Checksum Byte

Always calculate the checksum for a received character string and compare it with the checksum byte data to confirm that the character string was received correctly. Conduct error processing such as re-sending the command when a character string is received with an incorrect checksum.

Calculation Example

In the received character string "MJ01LS97\$" (\$ represents the carriage return code), the check sum code is represented by the last two characters: "97".

The checksum for the received character string is calculated as follows. The result shows that the received character string is correct.

	'M'	'J'	'0'	'1'	'L'	'S'		
Checksum =	4dH +	4aH +	30H +	31H +	4cH +	53H	= 197H	= 97H

A4.8 Outline of Multi-drop Communications

If the multi-drop function is turned on, set the network ID portion of a sent command to the network ID of the power supply unit with which communication is required.

All connected power supply units receive the sent command, but only the power supply unit with a network ID (set using setting mode/RS485 setting/network ID setting on the LCD display) that matches the network ID portion of the command returns an answer to the command it received.

Consequently, to acquire information from all connected power supply units requires repeated command/answer cycles with all power supply units while changing the network ID.

A5. TABLE OF COMMANDS

Table A-2 Table of Commands

Type	Command/ answer	Name	Command character string	Sub-command character string	
Operation mode	Command	Operation mode check	LS	None	
		On-line request	LN	None	
		Off-line request	LF	None	
	Answer	Local	LL	None	
		Remote	LR	None	
		RS-232C	LC	None	
		RS-485	LD	None	
Operation request	Command	START operation	RT	None	
		STOP operation	RP	None	
		RESET operation	RR	None	
	Answer	Acceleration start	RA	None	
		Deceleration start	RB	None	
		Buzzer off	RZ	None	
		Failure occurred	RF	aa	*1
		Failure elimination	RC	None	
Operation invalid	RV	None			
Run status	Command	Run status check	CS	None	
	Answer	Stop	NS	aa	*1
		Acceleration	NA	aa	*1
		Normal rotation	NN	aa	*1
		Deceleration	NB	aa	*1
		Failure-Stop	FS	aa	*1
		Failure-Free run	FF	aa	*1
		Failure-Regenerative braking	FR	aa	*1
	Failure-Deceleration	FB	aa	*1	
	Command	Read alarm list	CF	aa	*5
Answer	Send alarm list	CA	aabb	*6	
	No alarm list	CV	aa	*5	
Parameters	Command	Read parameter	PR	aa	*2
	Answer	Send parameter	PA	aabbbb	*3
		Invalid parameter number	PV	aa	*2
Event	Command	Failure occurred	EF	aa	*1
		Rotation start	ER	None	
		Rotation stop	ES	None	
		Normal rotation	EN	None	
	Answer	Event confirmation	EC	aa	*4
Timer	Command	Read timer	TR	aa	*7
		Clear timer	TC	aa	*7
		Write timer	TW	06aaaaa	*8
	Answer	Send timer value	TA	aabbbbccc...cccd dd...ddd	*9
		Invalid timer number	TV	aa	*7

History	Command	Read alarm history	GA	aa	*10
	Answer	Send alarm history	GB	xxx...xxx	*11
		No history data	GV	aa	*10
Settings	Command	Read settings	SR	aa	*12
		Write settings	SW	aabbbb	*13
	Answer	Send settings value	SA	aabbbb	*13
		Invalid setting number	SV	aa	*12
	Command	Read user memo	SU	None	
		Write user memo	SX	xxx...xxx	*14
	Answer	Send user memo	SF	xxx...xxx	*14
Shared answer	Answer	Invalid command	AN	None	

*1 aa: Failure alarm codes (hexadecimal) corresponding to the protection system. See Table 7-6 "Table of Alarms" and Table 7-7 "Table of Warnings" in this manual for details.

*2 aa: Parameter number (decimal). See Table A-3 "Table of Parameters."

*3 aa: Parameter number (decimal). See Table A-3 "Table of Parameters."

bbbb: Parameter value (decimal). See Table A-3 "Table of Parameters."

*4 aa: Confirm event command character string

Send the unchanged command character string of the confirmed event command.

Example: Failure occurred -> "EF"

*5 aa: Alarm list number (decimal)

*6 aa: Alarm list number (decimal)

bb: Alarm code (decimal) stored in the alarm list with the requested number.

See Table 7-6 "Table of Alarms" and Table 7-7 "Table of Warnings" in this manual for details.

*7 aa: Timer number (decimal). See Table A-4 "Table of Timers."

*8 06 (fixed): Timer number (decimal). See Table A-4 "Table of Timers."

aaaa: Set value (decimal). See Table A-4 "Table of Timers."

*9 aa: Timer number (decimal). See Table A-4 "Table of Timers."

bbbbbb: Timer value (decimal). See Table A-4 "Table of Timers."

ccccccccc: Time when the timer updated. (YYMMDDHHMM format. Stored as Greenwich Mean Time)

ddddddddd: Time when the timer reset. (YYMMDDHHMM format. Stored as Greenwich Mean Time)

*10 aa: History number

*11 xxx...xxx: See Table A-5 "Alarm History Data Format."

*12 aa: Settings number (decimal). See Table A-6 "Table of Settings."

*13 aa: Settings number (decimal). See Table A-6 "Table of Settings."

bbbb: Set value (decimal). See Table A-6 "Table of Settings."

*14 xxx...xxx: Any 20-character displayable character string.

Table A-3 Table of Parameters

No.	Name	Range	Description and format
01	Model identification number	Fixed	Value representing the model. Example: EI-D3203M → 3203
03	Rotational speed	0000 to 5000	Rotational speed / 10 Example: 15000 rpm → 1500
04	Motor current	0000 to 0150	Motor drive current x 10 Example: 2.3 A → 0023
05	Pump temperature	0000 to 0099	Pump temperature 45°C → 0045 (Valid only for a power supply with a temperature control function.)
07	Temperature control function	0000 to 0002	Temperature control function setting status 0000: Temperature control function on 0001: Temperature control function off 0002: Power supply has no temperature control function
08	Temperature control set temperature	Fixed	Target value of temperature control setting Example: 70°C → 0070 (Valid only for a power supply with a temperature control function.)
09	Rotational speed (%)	0000 to 0100	Percentage of rated rotational speed. Example: 80% → 0080
10	Rotational speed (%)	0000 to 1000	Percentage of rated rotational speed. (x10) Example: 80% → 0800
11	Rated rotational speed	0000 to 5000	Rated rotational speed / 10 Example: 21000 rpm → 2100
21	Axis 1 unbalance monitor amount	0000 to 100	Unbalance monitor value of magnetic bearing: Axis 1 Example: 3% → "0003"
22	Axis 2 unbalance monitor amount	0000 to 0100	Unbalance monitor value of magnetic bearing: Axis 2 Example: 3% → "0003"
26	MB sensor output X1	0000 to 0100	Sensor output monitor value of magnetic bearing: Axis X1 Example: 3% → "0003"
27	MB sensor output Y1	0000 to 0100	Sensor output monitor value of magnetic bearing: Axis Y1 Example: 3% → "0003"
28	MB sensor output X2	0000 to 0100	Sensor output monitor value of magnetic bearing: Axis X2 Example: 3% → "0003"
29	MB sensor output Y2	0000 to 0100	Sensor output monitor value of magnetic bearing: Axis Y2 Example: 3% → "0003"
30	MB sensor output Z	0000 to 0100	Sensor output monitor value of magnetic bearing: Axis Z Example: 3% → "0003"

Table A-4 Table of Timer

No.	Name	Range	Description and format
01	Run time	00000 to 99999	Read the timer value in the "MENU MODE / INTEGRAL TIMER / RUN TIME" on the LCD display. (Can not be reset. Reset date is invalid.) Example: 0 → 00000, 99999 → 99999
02	Last maintenance time	00000 to 99999	Read the timer value in the "MENU MODE / INTEGRAL TIMER / LAST MAINT." on the LCD display. (Can be reset) Example: 0 → 00000, 99999 → 99999
03	Power failure touch-down count	00000 to 00999	Read the timer value in the "MENU MODE / INTEGRAL TIMER / POWER FAILURE" on the LCD display. (Can be reset) Example: 0 → 00000, 999 → 00999
04	High-speed touch-down count	00000 to 00999	Read the timer value in the "MENU MODE / INTEGRAL TIMER / MB ALARM" on the LCD display. (Can be reset) Example: 0 → 00000, 999 → 00999
05	MB warning counter	00000 to 00999	Read the timer value in the "MENU MODE / INTEGRAL TIMER / MB WARNING" on the LCD display. (Can be reset) Example: 0 → 00000, 999 → 00999
06	Maintenance call time	00000 to 99999	Read or change the timer value in the "MENU MODE / INTEGRAL TIMER / MAINT.CALL" on the LCD display. Example: 0 → 00000, 99999 → 99999

Table A-5 Alarm History Data Format

	Item	Number of bytes	Data	Comments
1	History number	2	01 to 99	History number designated by the command.
2	Time	10	YYMMDDHHMM	Time when the failure occurred (stored as Greenwich Mean Time) YY: year, MM: month, DD: day, HH: hour, MM: minutes
3	Alarm number	2	00 to 99	Alarm number of the failure that occurred. See Table 10-5 "Table of Alarms" and Table 10-6 "Table of Warnings" in this manual for details.
4	Run status	2	NS, NA, NN...	Run status when the failure occurred. Data is identical to CS command answer.
5	Rotational speed	4	0000 to 0100	Speed when the failure occurred. Format is identical to 09 in Table A-3.
6	Motor current	4	0000 to 0150	Motor current in the event of a fault. The format is the same as No.04 in Table A-3.
7	Pump temperature	2	00 to 99	Pump temperature in the event of a fault. The format is equivalent to the last two characters of No.05 in Table A-3. (Valid only for a power supply with a temperature control function.)
8	Temperature control function	2	00, 01, 02	Temperature control function when the failure occurred. Format is equivalent to last 2 characters of 07 in Table A-3.

	Item	Number of bytes	Data	Comments
9	Temperature control set temperature	2	00 to 70	Temperature control set temperature when the failure occurred. Format is equivalent to last 2 characters of 08 in Table A-3. (Valid only for a power supply with a temperature control function.)
10	Axis 1 unbalance monitor amount	4	0000 to 0100	Unbalance monitor value of magnetic bearing when a fault occurs: Axis 1 Format is the same as No.21 in Table A-3.
11	Axis 2 unbalance monitor amount	4	0000 to 0100	Unbalance monitor value of magnetic bearing when a fault occurs: Axis 2 Format is the same as No.22 in Table A-3.
12	MB sensor output X1	4	0000 to 0100	Sensor output monitor value of magnetic bearing when a fault occurs: Axis X1 Format is the same as No.26 in Table A-3.
13	MB sensor output Y1	4	0000 to 0100	Sensor output monitor value of magnetic bearing when a fault occurs: Axis Y1 Format is the same as No.27 in Table A-3.
14	MB sensor output X2	4	0000 to 0100	Sensor output monitor value of magnetic bearing when a fault occurs: Axis X2 Format is the same as No.28 in Table A-3.
15	MB sensor output Y2	4	0000 to 0100	Sensor output monitor value of magnetic bearing when a fault occurs: Axis Y2 Format is the same as No.29 in Table A-3.
16	MB sensor output Z	4	0000 to 0100	Sensor output monitor value of magnetic bearing when a fault occurs: Axis Z Format is the same as No.30 in Table A-3.
17	Operation time	6	000000 to 099999	Operation time when a fault occurs. Format is the same as No.01 in Table A-4.

Table A-6 Table of Settings

No.	Name	Range	Description and format
01	Temperature control on/off	0000 / 0001	Read or change the set values in the "MENU / SETTINGS / TEMP.CONTORL / TEMP.CONTROL" on the LCD display. 0000: Temperature control function on 0001: Temperature control function off (Valid only for a power supply with a temperature control function.)
02	Speed display format	0000 to 0002	Read or change the set values in the "MENU / SETTINGS / ROT.SPEED / DISPLAY" on the LCD display. 0000: %, 0001: rpm, 0002: rps
03	Rotational speed	0000 / 0001	Read or change the set values in the "MENU / SETTINGS / ROT.SPEED / SPEED" on the LCD display. 0000: NORMAL, 0001: LOW SPEED
04	Low speed value	0025 to 0100	Read or change the set values in the "MENU / SETTINGS / ROT.SPEED / LOW SPEED" on the LCD display. Example: 25% -> 0025, 100% -> 0100
05	"ALARM" signal operation setting	0000 / 0001	Read or change the set values in the "MENU / SETTINGS / REMOTE SIGNAL MODE / ALARM" on the LCD display. 0000: SEMI-E74, 0001: EI-03
06	"REMOTE" signal operation setting	0000 / 0001	Read or change the set values in the "MENU / SETTINGS / REMOTE SIGNAL MODE / REMOTE" on the LCD display. 0000: SEMI-E74, 0001: EI-03
07	"STOP" signal operation setting	0000 / 0001	Read or change the set values in the "MENU / SETTINGS / REMOTE SIGNAL MODE / STOP" on the LCD display. 0000: REMOTE ONLY, 0001: REMOTE&RSXXX
08	Low rotation speed	0250 to 1000	Read or change the set values in the "MENU / SETTINGS / ROT.SPEED / LOW SPEED" on the LCD display. Example: 25.0% -> 0250, 99.9% -> 0999

A6. COMMAND DESCRIPTION

A6.1 Operation Mode

Commands	LS	Operation mode check Enables operation mode verification (LOCAL / REMOTE / RS-232C / RS-485) Action: Power supply returns an ANSWER showing present operation mode.
	LN	ON-LINE request If the current operation mode is REMOTE, the operation mode is shifted to RS-232C or RS-485. This command is ineffective in other operation modes. Action: Power supply returns an ANSWER showing the present operation mode.
	LF	OFF-LINE request If the current operation mode is RS-232C or RS-485, the operation mode is shifted to REMOTE. This command is ineffective in other operation modes. Action: Power supply returns an ANSWER showing the present operation mode.
Answers	LL	Operation mode LOCAL This answer is returned when the operation mode is LOCAL. The operation mode can also be shifted to LOCAL mode by the front panel REMOTE/LOCAL selection switch.
	LR	Operation mode REMOTE This answer is returned when the operation mode is REMOTE. The operation mode can also be shifted to REMOTE mode by the front panel REMOTE/LOCAL selection switch or when in the RS-232C or RS-485 operation mode by the "OFF-LINE" request command.
	LC	Operation mode RS-232C This answer is returned when the operation mode is RS-232C. The operation mode is shifted to RS-232C when the "ON-LINE" request command is sending via RS-232C in the remote operation mode.
	LD	Operation mode RS-485 This answer is returned when the operation mode is RS-485. The operation mode is shifted to RS-485 when the "ON-LINE" request command is sending via RS-485 in the remote operation mode.

A6.2 Operation

Commands	RT	<p>START Operation</p> <p>This command is the equivalent of pressing the front panel START switch.</p> <p>Action: The turbo molecular pump starts accelerating and sends the "Acceleration Start" answer.</p>
	RP	<p>STOP Operation</p> <p>This command is the equivalent of pressing the front panel STOP switch.</p> <p>Action: The turbo molecular pump starts decelerating and sends the "Deceleration Start" answer.</p>
	RR	<p>RESET Operation</p> <p>This command is the equivalent of pressing the front panel RESET switch.</p> <p>Action: This command is effective against failures. This command resets the alarm buzzer sound and returns the "Buzzer Off" answer. If the buzzer is already off, this command resets the ALARM. If the cause of the alarm is eliminated after resetting, the "Failure Elimination" answer will be returned, else the buzzer will sound again and the "Failure occurrence " Answer is sent back.</p>
Answers	RA	<p>Acceleration Start</p> <p>This answer is returned by the power supply after the acceleration is started on a START operation.</p>
	RB	<p>Deceleration Start</p> <p>This answer is returned by the power supply after the deceleration is started on a STOP operation.</p>
	RZ	<p>Buzzer Off</p> <p>This answer is returned by the power supply after the buzzer is turned off on a RESET operation.</p>
	RC	<p>Failure elimination</p> <p>This answer is returned by the power supply after the failure cause is removed after the power supply is reset on a RESET operation.</p>
	RF	<p>Failure Occurrence</p> <p>This answer is returned by the power supply if the failure cause is not removed after the power supply is reset on a RESET operation. The alarm code of the failure that has not been eliminated is returned as a 2-character sub-command.</p>
	RV	<p>Operation invalid</p> <p>This answer is returned if the operation is invalid (START operation command sent during acceleration) or if the operation mode differs from the port that sent the command (operation mode is RS-485 but operation command was sent from the RS-232C port).</p>

A6.3 Run Status

A

Commands	CS	Run Status Check This command requests the current power supply status.
Answers	NS	Stop This answer is returned when the pump stops. Equivalent to the monitor mode/STOP run status on the LCD display. For a normal status, "00" is returned as the sub-command. If a warning has occurred, the 2-character alarm code is returned as the sub-command.
	NA	Acceleration This answer is returned during pump acceleration. Equivalent to the monitor mode/ACC. run status on the LCD display. For a normal status, "00" is returned as the sub-command. If a warning has occurred, the 2-character alarm code is returned as the sub-command.
	NN	Normal rotation This answer is returned during normal pump rotation. Equivalent to the monitor mode/NORMAL run status on the LCD display. For a normal status, "00" is returned as the sub-command. If a warning has occurred, the 2-character alarm code is returned as the sub-command.
	NB	Deceleration This answer is returned during pump deceleration. Equivalent to the monitor mode/BRAKE run status on the LCD display. For a normal status, "00" is returned as the sub-command. If a warning has occurred, the 2-character alarm code is returned as the sub-command.
	FS	Failure-Stop This answer is returned when the pump is stopped after a failure occurs. Equivalent to the monitor mode/E-STOP run status on the LCD display. The 2-character alarm code is returned as the sub-command.
	FF	Failure-Free run This answer is returned when the pump is free-running (neither accelerating nor decelerating) after a failure occurs. Equivalent to the monitor mode/E-IDLE run status on the LCD display. The 2-character alarm code is returned as the sub-command.
	FR	Failure-Regenerative braking This answer is returned when the pump is regenerative braking after a failure occurs. Equivalent to the monitor mode/E-BRAKE run status on the LCD display. The 2-character alarm code is returned as the sub-command.
	FB	Failure-Deceleration This answer is returned when the pump is decelerating after a failure occurs. Equivalent to the monitor mode/E-BRAKE run status on the LCD display. The 2-character alarm code is returned as the sub-command.
Commands	CF	Read alarm list Reads the alarm that occurred for a designated alarm list number. The alarm list numbers are equivalent to the sequence displayed on the LCD in the LCD display alarm mode. To check all the current failures, the sub-command alarm list number is increased sequentially from 01 until the answer CV is returned.
Answers	CA	Send alarm list Returns the alarm code corresponding to the requested alarm list number. The sub-command returns a 2-character alarm list number and a 2-character alarm code.
	CV	No alarm list This answer is returned if no alarm corresponds to the requested alarm list number. The sub-command returns a 2-character alarm list number.

A6.4 Parameters

Commands	PR	Read parameter Reads the parameter value for a designated parameter number. Sends the 2-character parameter number as the sub-command.
Answers	PA	Send parameter Returns the parameter value for the designated parameter number. The 2-character parameter number + 4-character parameter value is returned as the sub-command in the format shown in Table A-3 "Table of Parameters."
	PV	Invalid parameter number This answer is returned if the designated parameter number is invalid. Returns the 2-character parameter number as the sub-command.

A6.5 Events

For the event functions only, commands are sent from the power supply unit to the connected computer, and the answers are sent from the computer to the power supply unit.

This function can also be disabled by setting the SETTINGS/RS232C/EVENT SENDING or SETTINGS/RS485/EVENT SENDING menu setting to OFF on the LCD display.

This function will be disabled automatically if the RS485 multi-drop function is enabled.

Commands	EF	Failure occurred Sent to the connected computer when an failure occurs. The 2-character alarm code for the failure is sent as the sub-command.
	ER	Start rotation Sent to the connected computer when pump rotation starts. Equivalent to the ROTATION lamp lighting.
	ES	Stop rotation Sent to the connected computer when pump rotation stops. Equivalent to the ROTATION lamp going out.
	EN	Normal speed Sent to the connected computer when the normal rotation speed is achieved. Equivalent to the NORMAL SPEED lamp lighting.
Answers	EC	Confirm event Return this answer to the power supply unit when an event is received from the power supply unit. The power supply unit sends the command up to five times at one-second intervals until it receives the confirm event answer. Send the 2-character command character string for the received event command as a sub-command.

A6.6 Timer

Commands	TR	Read timer Reads the timer value for a designated timer number. Sends the 2-character timer number as the sub-command.
	TC	Clear timer Clears the timer value for a designated timer number. Sends the 2-character timer number as the sub-command.
	TW	Write timer Overwrites the set value for a maintenance call timer. Sends the 2-character settings number + 5-character set value data as the sub-command.
Answers	TA	Send timer value Returns the timer value for the designated timer number. The 2-character timer number + 5-character timer value is returned as the sub-command in the format shown in Table A-4 "Table of Timers."
	TV	Invalid timer number This answer is returned if the designated timer number is invalid. Returns the 2-character timer number as the sub-command.

A6.7 History

Commands	GA	Read alarm history Reads the alarm history for a designated alarm history number. Sends the 2-character alarm history number as the sub-command.
Answers	GB	Send alarm history Returns the alarm history for the designated alarm history number. The 64-character alarm history data is returned as the sub-command in the format shown in Table A-5 "Alarm History Data Format."
	GV	No history data This answer is returned if no alarm history data corresponds to the designated alarm history number. Returns the 2-character alarm history number as the sub-command.

A6.8 Settings

Commands	SR	Read settings Reads the set value for a designated settings number. Sends the 2-character settings number as the sub-command.
	SW	Write settings Overwrites the set value for a designated settings number. Sends the 2-character settings number + 4-character set value data as the sub-command.
Answers	SA	Send settings value Returns the set value for the designated settings number. The 2-character settings number + 4-character set value is returned as the sub-command.
	SV	Invalid setting number This answer is returned if the designated settings number is invalid. Returns the 2-character settings number as the sub-command.
Commands	SU	Read user memo Reads the character string in the user memo.
	SX	Write user memo Overwrites the character string in the user memo. Sends the 20 characters to set in the user memo as the sub-command. If less than 20 characters are set, the remaining characters are filled with spaces. Be sure to always send 20 characters.
Answers	SF	Send user memo Returns as a sub-command the set user memo character string or the 20-character user memo character string overwritten by the SX command.

A6.9 Shared Answer

Answers	AN	Invalid Command Answer returned by the power supply after it receives an invalid command.
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A7. RS-232C COMMANDS / ANSWERS (SEND AND RECEIVE Examples)

A

Table A-7 RS-232C COMMANDS / ANSWERS (SEND AND RECEIVE Examples)

Type	Computer (Host) *1	Send/Receive *2	Power Supply	Description	Remarks
Operation Mode	MJ01LS97\$			Operation Mode Check	
			MJ01LL90\$	LOCAL	
			MJ01LR96\$	REMOTE	
			MJ01LC87\$	RS-232C	
			MJ01LD88\$	RS-485	
	MJ01LN92\$			ON-LINE Request	ON-LINE request from RS-232C communication port
			MJ01LC87\$	Operation Mode Change	Operation mode changed to RS-232C ON-LINE
			MJ01LD88\$	Invalid Request	When in RS-485 mode
			MJ01LL90\$	Invalid Request	When in LOCAL mode
	MJ01LF8A\$			OFF-LINE Request	OFF-LINE request from RS-232C communication port
			MJ01LR96\$	Operation Mode Change	Operation mode changed to REMOTE
			MJ01LD88\$	Invalid Request	When in RS-485 mode
		MJ01LL90\$	Invalid Request	When in LOCAL mode	
TMP Operation	MJ01RT9E\$			START Operation	START operation from RS-232C communication port
			MJ01RA8B\$	Acceleration Start	
			MJ01RVA0\$	Ineffective Operation	When START operation is ineffective or operation mode is not RS-232C
	MJ01RP9A\$			STOP Operation	STOP operation from RS-232C communication port
			MJ01RB8C\$	Deceleration Start	
			MJ01RVA0\$	Ineffective Operation	When STOP operation is ineffective or operation mode is not RS-232C
	MJ01RR9C\$			RESET Operation	RESET operation from RS-232C communication port
			MJ01RZA4\$	Buzzer Off	When a buzzer sounded
			MJ01RF50F5\$	Failure Occurrence	When the failure was not eliminated.
			MJ01RC8D\$	Failure Eliminated	When the failure was eliminated.
			MJ01RVA0\$	Ineffective Operation	When RESET operation is ineffective or operation mode is not RS-232C

Appendix A COMMUNICATIONS

A

Type	Computer (Host) *1	Send/Receive *2	Power Supply	Description	Remarks
Run Status	MJ01CS8E\$			Run Status Check	
			MJ01NS00F9\$	Stop	
			MJ01NA00E7\$	Acceleration	
			MJ01NB00E8\$	Deceleration	
			MJ01NN00F4\$	Normal Rotation	
			MJ01FS1C05\$	Failure Stop	LCD: "TMP:CAN NOT START"
			MJ01FF30E7\$	Failure Idle	LCD: "EI:DC-DC OVERTEMP"
			MJ01FR50F5\$	Failure Regeneration	LCD: "POWER FAILURE"
			MJ01FB20E2\$	Failure Deceleration	LCD: "MB:OVERLOAD"
	MJ01CF01E2\$			Read Alarm List	Confirm first alarm
			MJ01CA015042\$	Send Alarm List	Power supply failure
Parameter	MJ01PR03FD\$			Read Parameter	Parameter 03 (rotational speed)
			MJ01PA032700B5\$	Send Parameter	Data = 2700 (27,000 rpm)
	MJ01PR10FB\$			Read parameter	Parameter 10 (invalid number)
			MJ01PV10FF\$	Invalid parameter number	
Event			MJ01EF50E8\$	Failure Occurrence	Power supply failure
	MJ01ECEFOB\$			Event Confirmation	
			MJ01ER8F\$	Rotation Start	
	MJ01ECER17\$			Event Confirmation	
			MJ01ES90\$	Rotation Stop	
	MJ01ECES18\$			Event Confirmation	
			MJ01EN8B\$	Normal Rotation	
Timer	MJ01TR01FF\$			Read Timer	Timer 01 (Run time)
			MJ01TA0100135030405150000000000B9\$	Send Timer	Timer 01 = 135 (135 hours) Last update: 2003/4/5 15:00 Last reset: (invalid)
	MJ01TW030000F6\$			Clear Timer	Clear timer 03 (Number of power failure touch-downs.)
			MJ01TA030000E0\$	Timer Value	Timer 03 = 0 Value cleared.

Type	Computer (Host) *1	Send/Receive *2	Power Supply	Description	Remarks
History	MJ01GA01E1\$			Read Alarm History	History 01
			MJ01GB01030 401120015NN 010000103500 000400060003 000300050005 000200120098\$	Send Alarm History	History: 01 Date & time: 2003/04/01 12:00 Alarm: power failure Status: normal rotation Rotational speed: 100% Motor current: 1.0 A Pump temperature: 35°C Temperature control function: on Unbalance monitor Axis1:4%, Axis2:6% MB sensor output X1:3%, Y1:3%, X2:5%, Y2:5%, Z:2% Runtime:1200hours
	MJ01GA10E1\$			Read Alarm History	History 10
			MJ01GV10F6\$	No History Data	Less than 10 alarm data
Setting	MJ01SR02FF\$			Read Settings	Settings number 02
			MJ01SA02000AE\$	Send Settings Value	Settings number 02=0 →Speed display: %
	MJ01SW02001C5\$			Write Settings	Overwrite settings number 02 = 1
			MJ01SA020001AF\$	Send Settings Value	Settings number 02=1 →Speed display: rpm
Others	MJ01AA7A\$			Undefined Command	When undefined command is received
			MJ01AN87\$	Invalid Command	
	MJ01LS20\$			Operation Mode Check	When command is correct, but checksum is not.
			MJ01AN87\$	Invalid Command	

*1 Note: "\$" represents a carriage return code (0dH).

*2 Note: From computer to power supply unit.
From power supply unit to computer.

A8. RELATION OF LOCAL MODE TO REMOTE MODE OPERATIONS

- (1) Input of front panel switch is only effective when REMOTE / LOCAL selection switch is in "LOCAL" mode.
- (2) When the selection switch is in "REMOTE" mode, "REMOTE" input signal only is effective under initial status.
- (3) When the selection switch is in "REMOTE" mode,
 - a. The operation mode is shifted to RS-232C ON-LINE in response to ON LINE request of operation mode command from RS-232C communication port, only operation by the operation request command from computer is effective.
 - b. The operation mode is shifted to RS-485 ON-LINE in response to ON LINE request of operation mode command from RS-485 communication port, only operation by the operation request command from computer is effective.
- (4) RESET switch input and "RESET" signals are all-time effective.
- (5) When the selection switch is shifted to "LOCAL" under ON-LINE operation mode, the operation mode is force-shifted to LOCAL.
- (6) Commands other than operation commands are all-time effective, and the power supply unit sends back an answer message to computer. In addition, event commands are all-time sent against event occurrence.

A9. TROUBLESHOOTING

A9.1 No Message can Transmit and Receive

(1) Start the pump in LOCAL mode and check if the event command of Rotation start can be received in the timing at which ROTATION lamp lights.

Could be received >> check if command from connected computer can be received or not, using another computer, etc.

A nonsensical character string was received >> Go to A9.2.

c. Not receivable >> (2)

(2) Check the connection of RS-232C cable in reference to A2.

Check the polarity of RS-485 interface, because there is the case that polarity is reverse.

(3) Check the transmission specification of RS-232C at computer side.

A9.2 Sending and Receiving are Done, But Receivable Messages are Invalid

(1) Check the transmission rate of the power supply unit and computer.

A9.3 Characters Get Disordered from Time to Time, Then Resulting in CHECKSUM Error

(1) Remove the cable from equipment as noise source if it runs near it.

(2) When the cable in use is not a shield cable, replace it with the latter cable.

When shield cable is used, be sure to check that it is connected to the frame gland of the connected computer.

Use twisted pair cable when RS-485 is used.

(3) When 10 m or longer cable is used, replace it with another cable as short as possible.

(4) Make the transmission rate smaller unless there is problem in application program .

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TMP Evaluation Form

Please fill out this evaluation form and attach to the product when you send it back to Shimadzu Service Center for repair service, etc. When you fill out this form, please describe the details as much as possible.

Evaluation items (Please check the item box, and fill out the information at the underline.)

Returned : Pump Type TMP- Product No.
 Power source Type EI- Product No.

Request : Overhaul repair others

Detail _____

Alarm name : _____ (If there is status indication lamp, light No is : _____)

System/Equipment name : _____

Date of request (date of occurrence) : _____ Expected date of treatment completion : _____

Total operation hours : _____ hrs. Date of operation start : _____ Date of delivery : _____

Please fill out the following items to make sure of worker's safety.

[Announcement of attraction material and gas]

Repair etc. may not be accepted when attraction material and gas is not removed.

• Type of attraction material : _____
 (Please fill out the etched material in etch system/equipment (GaAs substrate etc.). Please fill out the material of target in PVD system/equipment (sputter, vacuum evaporation etc.).)

• Type of attraction gas

Air, nitrogen, etc. (name :) Inert gas such as helium, etc. (name :)

Corrosive gas (name :) Reactive/active gas (name :)

Virulent gas (name :) Others (name :)

Attraction gas (: removed, : not removed) Influence on man's body.(YES, NO)

Treatment procedure, handling precaution, etc. for case when attraction gas is not removed.

• Is there a color changes and adhesion at inlet and outlet flange? Yes No

If there is a color changes and adhesion, we wash the TMP to keep an appropriate performance of vacuum pump.(additional charges)

Customer(Company) : Division : _____ Phone # : _____

Contact Person : _____(ext.#) _____ Authorized signature : _____

Use condition of equipment :

Gas purge : Used (ml/min) Not used (none)

For the oil type bearing :

Oil type : Standard oil Fluorine base oil(designated oil) Others()

Oil level : near upper limit medium point near lower limit less than lower limit

Others :

Dealer name : _____ Contact Person : _____ Tel _____



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